

# VIPA System MICRO

## SM-AIO | | Manual

HB400 | SM-AIO | | en | 18-44

Analog signal modules - SM M3x



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General VIPA System MICRO

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## 1 General

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VIPA System MICRO General

About this manual

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Tel.: +49 9132 744-1150 (Hotline)

EMail: support@vipa.de

## 1.2 About this manual

### Target audience

The manual is targeted at users who have a background in automation technology.

#### Structure of the manual

The manual consists of chapters. Every chapter provides a self-contained description of a specific topic.

#### Guide to the document

The following guides are available in the manual:

- An overall table of contents at the beginning of the manual
- References with page numbers

#### **Availability**

The manual is available in:

- printed form, on paper
- in electronic form as PDF-file (Adobe Acrobat Reader)

## **Icons Headings**

Important passages in the text are highlighted by following icons and headings:



#### **DANGER!**

Immediate or likely danger. Personal injury is possible.



## **CAUTION!**

Damages to property is likely if these warnings are not heeded.



Supplementary information and useful tips.

General VIPA System MICRO

Safety information

## 1.3 Safety information

# Applications conforming with specifications

The system is constructed and produced for:

- communication and process control
- general control and automation tasks
- industrial applications
- operation within the environmental conditions specified in the technical data
- installation into a cubicle



#### **DANGER!**

This device is not certified for applications in

in explosive environments (EX-zone)

#### **Documentation**

The manual must be available to all personnel in the

- project design department
- installation department
- commissioning
- operation



#### **CAUTION!**

The following conditions must be met before using or commissioning the components described in this manual:

- Hardware modifications to the process control system should only be carried out when the system has been disconnected from power!
- Installation and hardware modifications only by properly trained personnel.
- The national rules and regulations of the respective country must be satisfied (installation, safety, EMC ...)

## Disposal

National rules and regulations apply to the disposal of the unit!

VIPA System MICRO

Basics and mounting

Safety information for users

## 2 Basics and mounting

## 2.1 Safety information for users

Handling of electrostatic sensitive modules

VIPA modules make use of highly integrated components in MOS-Technology. These components are extremely sensitive to over-voltages that can occur during electrostatic discharges. The following symbol is attached to modules that can be destroyed by electrostatic discharges.



The Symbol is located on the module, the module rack or on packing material and it indicates the presence of electrostatic sensitive equipment. It is possible that electrostatic sensitive equipment is destroyed by energies and voltages that are far less than the human threshold of perception. These voltages can occur where persons do not discharge themselves before handling electrostatic sensitive modules and they can damage components thereby, causing the module to become inoperable or unusable. Modules that have been damaged by electrostatic discharges can fail after a temperature change, mechanical shock or changes in the electrical load. Only the consequent implementation of protection devices and meticulous attention to the applicable rules and regulations for handling the respective equipment can prevent failures of electrostatic sensitive modules.

#### Shipping of modules

Modules must be shipped in the original packing material.

Measurements and alterations on electrostatic sensitive modules When you are conducting measurements on electrostatic sensitive modules you should take the following precautions:

- Floating instruments must be discharged before use.
- Instruments must be grounded.

Modifying electrostatic sensitive modules you should only use soldering irons with grounded tips.



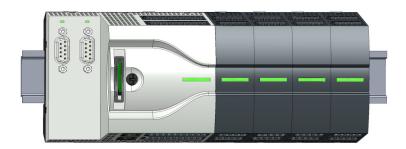
#### **CAUTION!**

Personnel and instruments should be grounded when working on electrostatic sensitive modules.

System conception

## 2.2 System conception

#### Overview



The System MICRO is a modular automation system for assembly on a 35mm mounting rail. By means of periphery modules this system may be adapted matching to your automation tasks. In addition, it is possible to expand your CPU by appropriate interfaces. The wiring complexity is low, because the DC 24V electronic section supply is integrated to the backplane bus and this allows replacement with standing wire.

### Components

- CPU
- Extension module
- Periphery module

#### **CPU**



With the CPU electronic, input/output components and power supply are integrated to one casing. In addition, up to 8 periphery modules of the System MICRO can be connected to the backplane bus. As head module via the integrated power module for power supply CPU electronic and the I/O components are supplied as well as the electronic of the periphery modules, which are connected via backplane bus. To connect the power supply of the I/O components and for DC 24V electronic power supply of the periphery modules, which are connected via backplane bus, the CPU has removable connectors. By installing of up to 8 periphery modules at the backplane bus of the CPU, these are electrically connected, this means these are assigned to the backplane bus and connected to the DC 24V electronic power supply.

### **Extension module**



By using extension modules you can extend the interfaces of the CPU. The attachment to the CPU is made by plugging on the left side of the CPU. You can only connect one extension module to the CPU at a time.

Dimensions

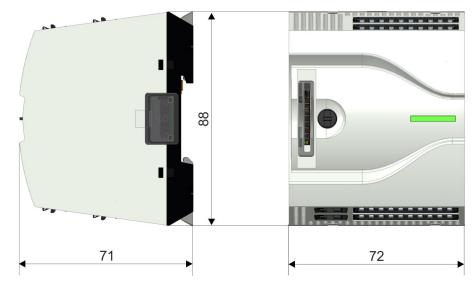
## Periphery module



By means of up to 8 periphery modules, you can extend the internal I/O areas. The attachment to the CPU is made by plugging them on the right side of the CPU.

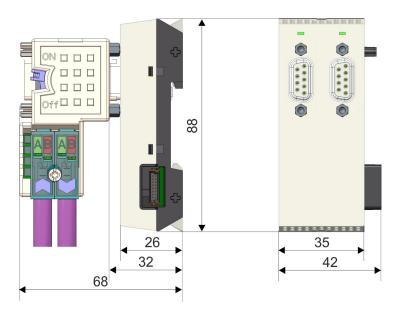
## 2.3 Dimensions

## **Dimensions CPU M13C**



Dimensions in mm

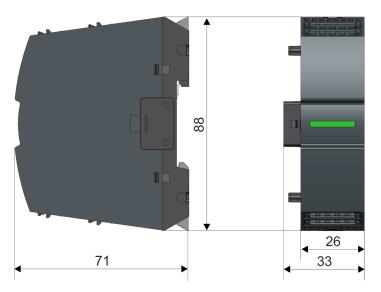
# Dimensions extension module EM M09



Dimensions in mm

Mounting > Mounting CPU

# Dimensions periphery module



Dimensions in mm

## 2.4 Mounting

## 2.4.1 Mounting CPU

## 2.4.1.1 Mounting CPU without mounting rail



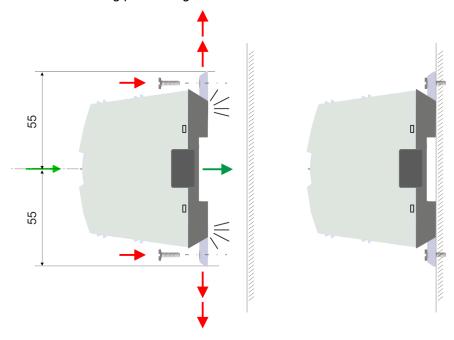
## **CAUTION!**

Mounting without mounting rail is only permitted, if you only want to use the CPU without extension and periphery modules. Otherwise, a mounting rail must always be used for EMC technical reasons.

Mounting > Mounting CPU

#### **Proceeding**

You can screw the CPU to the back wall by means of screws via the locking levers. This happens with the following proceeding:

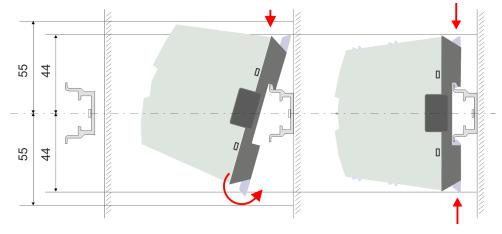


Dimensions in mm

- 1. The CPU has a locking lever on the upper and lower side. Pull these levers outwards as shown in the figure, until these engage 2x audible.
  - ⇒ By this openings on the locking levers get visible.
- **2.** Use the appropriate screws to fix your CPU to your back wall. Consider the installation clearances for the CPU.
  - ⇒ The CPU is now mounted and can be wired.

## 2.4.1.2 Mounting with mounting rail

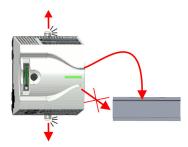
## **Proceeding**



Dimensions in mm

1. Mount the mounting rail. Please consider that a clearance from the middle of the mounting rail of at least 44mm respectively 55mm above and below exists.

Mounting > Mounting CPU



2. The CPU has a locking lever on the upper and lower side. Pull these levers outwards as shown in the figure, until these engage audible.

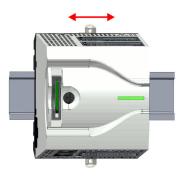


## **CAUTION!**

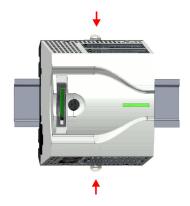
It is not allowed to mount the module sideways on the mounting rail, as otherwise the module may be damaged.



**3.** Plug the CPU from the top onto the mounting rail and turn the CPU downward until it rests on the mounting rail.



**4.** Move the CPU on the mounting rail at its position.



- **5.** To fix the CPU at the mounting rail, move the locking levers back to the initial position.
  - ⇒ The CPU is now mounted and can be wired.

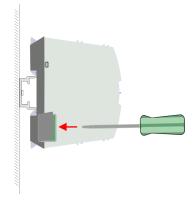
Mounting > Mounting the extension module

## 2.4.2 Mounting the extension module

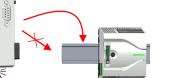
## **Proceeding**

You have the possibility to extend the interfaces of the CPU by plugging an extension module. For this the extension module is plugged at the left side of the CPU. The mountings happens with the following proceeding:

1. Remove the bus cover with a screwdriver on the left side of the CPU.

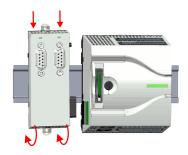


The extension module has a locking lever on the upper and lower side. Pull these levers outwards as shown in the figure, until these engage audible.

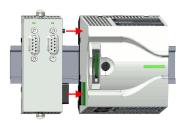


## **CAUTION!**

It is not allowed to mount the module sideways on the mounting rail, as otherwise the module may be damaged.



To mount plug the extension module from the top onto the mounting rail and turn the extension module downward until it rests on the mounting rail.



4. Attach the extension module to the CPU by sliding the extension module on the mounting rail to the right until the interface connector slightly locks into the CPU.



**5.** To fix the extension module at the mounting rail, move the locking levers back to the initial position.

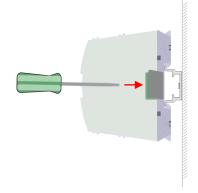
Mounting > Mounting periphery module

## 2.4.3 Mounting periphery module

## **Proceeding**

You have the possibility to extend the periphery area of the CPU by plugging up to 8 periphery modules. For this the periphery modules are plugged at the right side of the CPU. The mountings happens with the following proceeding:

**1.** Remove the bus cover with a screwdriver on the right side of the CPU.



**2.** Each periphery module has a locking lever on its upper and lower side. Pull these levers outwards as shown in the figure, until these engage audible.

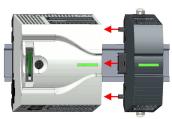


### **CAUTION!**

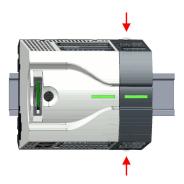
It is not allowed to mount the module sideways on the mounting rail, as otherwise the module may be damaged.



To mount plug the periphery module from the top onto the mounting rail and turn the periphery module downward until it rests on the mounting rail.



Attach the periphery module to the CPU by sliding the periphery module on the mounting rail to the left until the interface connector slightly locks into the CPU.



- To fix the periphery module at the mounting rail, move the locking levers back to the initial position.
- **6.** Proceed in this way with additional periphery modules.

VIPA System MICRO **Basics and mounting** 

Wirina > Wirina CPU

## 2.5 Wiring



#### **CAUTION!**

## Consider temperature for external cables!

Cables may experience temperature increase due to system heat dissipation. Thus the cabling specification must be chosen 5°C above ambient temperature!



### **CAUTION!**

## Separate insulation areas!

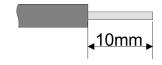
The system is specified for SELV/PELV environment. Devices, which are attached to the system must meet theses specifications. Installation and cable routing other than SELV/PELV specification must be separated from the system's equipment!

## 2.5.1 Wiring CPU

## **CPU** connector

For wiring the CPU has removable connectors. With the wiring of the connectors a "pushin" spring-clip technique is used. This allows a quick and easy connection of your signal and supply lines. The clamping off takes place by means of a screwdriver.

#### Data



 $\mathbf{U}_{\text{max}}$ 30V DC 10A

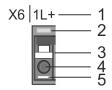
 $I_{max}$ 

Cross section 0.2 ... 1.5mm<sup>2</sup> (AWG 24 ... 16)

Stripping length 10mm

Use for wiring rigid wires respectively use wire sleeves. When using stranded wires you have to press the release button with a screwdriver during the wiring.

### Wiring procedure

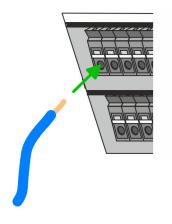


- Labeling on the casing
- Status LED
- 3 Release area
- 4 Connection hole for wire
- 5 Pin 1 of the connector is labelled by a white line

VIPA System MICRO **Basics and mounting** 

Wiring > Wiring CPU

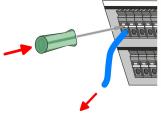
#### Insert wire



The wiring happens without a tool.

- Determine according to the casing labelling the connection position and insert through the round connection hole of the according contact your prepared wire until it stops, so that it is fixed.
  - By pushing the contact spring opens, thus ensuring the necessary contact pres-

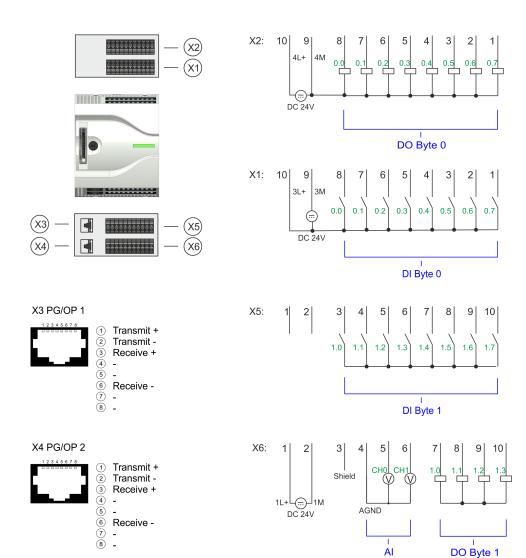
#### Remove wire



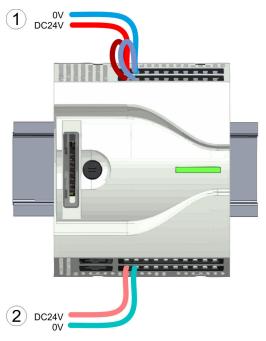
The wire is to be removed by means of a screwdriver with 2.5mm blade width.

- 1. Press with your screwdriver vertically at the release button.
  - ⇒ The contact spring releases the wire.
- **2.** Pull the wire from the round hole.





Wiring > Wiring CPU



- (1) X2: 4L+: DC 24V power section supply for integrated outputs X1: 3L+: DC 24V power section supply for integrated inputs
- (2) X6: 1L+ DC 24V for electronic power supply



The electronic power section supply is internally protected against higher voltage by fuse. The fuse is located inside the CPU and can not be changed by the user.

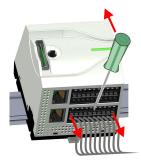
### **Fusing**



## **CAUTION!**

 The power section supply of the internal DOs is to be externally protected with a 8A fuse (fast) respectively by a line circuit breaker 8A characteristics Z.

#### Remove connector

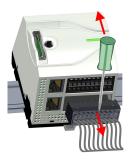


By means of a screwdriver there is the possibility to remove the connectors e.g. for module exchange with a fix wiring. For this each connector has indentations for unlocking at the top. Unlocking takes place by the following proceeding:

**1.** Remove connector:

Insert your screwdriver from above into one of the indentations.

Wiring > Wiring CPU



**2.** Push the screwdriver backwards:

⇒ The connector is unlocked and can be removed.



## **CAUTION!**

Via wrong operation such as pressing the screwdriver downward, the release lever may be damaged.

3. Plug connector:

The connector is plugged by plugging it directly into the release lever.

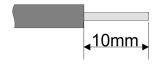
Wiring > Wiring periphery module

## 2.5.2 Wiring periphery module

#### Periphery module connector

For wiring the periphery module has removable connectors. With the wiring of the connectors a "push-in" spring-clip technique is used. This allows a quick and easy connection of your signal and supply lines. The clamping off takes place by means of a screwdriver.

#### Data



U<sub>max</sub> 240V AC / 30V DC

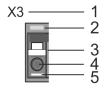
 $I_{\text{max}}$  10A

Cross section 0.2 ... 1.5mm<sup>2</sup> (AWG 24 ... 16)

Stripping length 10mm

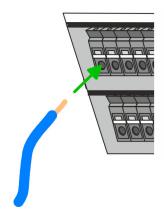
Use for wiring rigid wires respectively use wire sleeves. When using stranded wires you have to press the release button with a screwdriver during the wiring.

## Wiring procedure



- 1 Labeling on the casing
- 2 Status LED
- 3 Release area
- 4 Connection hole for wire
- 5 Pin 1 of the connector is labelled by a white line

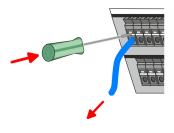
#### Insert wire



The wiring happens without a tool.

- Determine according to the casing labelling the connection position and insert through the round connection hole of the according contact your prepared wire until it stops, so that it is fixed.
  - By pushing the contact spring opens, thus ensuring the necessary contact pressure.

## Remove wire



The wire is to be removed by means of a screwdriver with 2.5mm blade width.

- **1.** Press with your screwdriver vertically at the release button.
  - ⇒ The contact spring releases the wire.
- **2.** Pull the wire from the round hole.

## **Fusing**



## **CAUTION!**

- The power section supply of the output modules DO16 is to be externally protected with a 10A fuse (fast) respectively by a line circuit breaker 10A characteristics Z.
- The power section supply of the output part of the DIO8 is to be externally protected with a 5A fuse (fast) respectively by a line circuit breaker 5A characteristics Z.

Wiring > Wiring periphery module

#### Remove connector



By means of a screwdriver there is the possibility to remove the connectors e.g. for module exchange with a fix wiring. For this each connector has indentations for unlocking at the top. Unlocking takes place by the following proceeding:

1. Remove connector:

Insert your screwdriver from above into one of the indentations.



- 2. Push the screwdriver backwards:
  - ⇒ The connector is unlocked and can be removed.



### **CAUTION!**

Via wrong operation such as pressing the screwdriver downward, the release lever may be damaged.

3. Plug connector:

The connector is plugged by plugging it directly into the release lever.

Demounting > Demounting CPU

## 2.6 Demounting

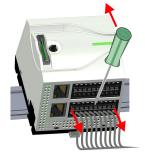
## 2.6.1 Demounting CPU

#### Remove connector

By means of a screwdriver there is the possibility to remove the connectors e.g. for module exchange with a fix wiring. For this each connector has indentations for unlocking at the top. Unlocking takes place by the following proceeding:

- **1.** Power-off your system.
- 2. Remove connector:

Insert your screwdriver from above into one of the indentations.



- 3. Push the screwdriver backwards:
  - ⇒ The connector is unlocked and can be removed.



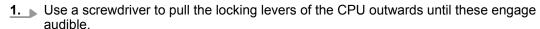
#### **CAUTION!**

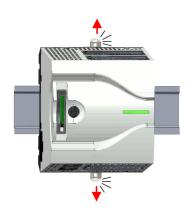
Via wrong operation such as pressing the screwdriver downward, the connector may be damaged!

**4.** In this way, remove all plugged connectors on the CPU.

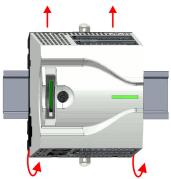
# CPU replacement (standalone)

If more modules are connected to the CPU  $\$  'Option: CPU replacement in a system' page 23. If no other modules are connected to the CPU, the CPU is replaced according to the following proceeding:

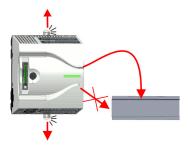




**2.** Remove the CPU with a rotation upwards from the mounting rail.



Demounting > Demounting CPU

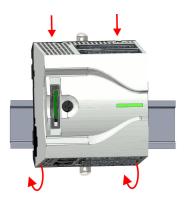


3. Pull the locking levers of the CPU outwards until these engage audible.

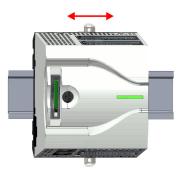


## **CAUTION!**

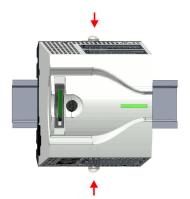
It is not allowed to mount the module sideways on the mounting rail, as otherwise the module may be damaged!



Plug the CPU from the top onto the mounting rail and turn the CPU downward until it rests on the mounting rail.



**5.** Move the CPU on the mounting rail at its position.



**6.** To fix the CPU at the mounting rail, move the locking levers back to the initial position.



**7.** Remove the connectors, which are not necessary at the CPU.

VIPA System MICRO

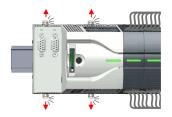
Basics and mounting

Demounting > Demounting CPU



- **8.** Plug again the wired connectors.
  - ⇒ Now you can bring your system back into operation.

# Option: CPU replacement in a system



In the following the replacement of a CPU in a system is shown:

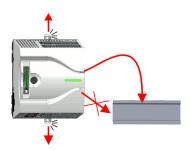
1. If there is an extension module connected to the CPU, you have to remove it from the CPU. For this use a screwdriver to pull the locking levers of the extension module and CPU outwards until these engage audible.



**2.** Disconnect all the modules, which are connected to the CPU by moving the CPU along with the extension module on the mounting rail.



**3.** Remove the CPU with a rotation upwards from the mounting rail.

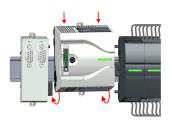


**4.** Pull the locking levers of the CPU outwards until these engage audible.



#### **CAUTION!**

It is not allowed to mount the module sideways on the mounting rail, as otherwise the module may be damaged!



For mounting pull the locking levers of the CPU outwards until these engage audible. Plug the CPU from the top onto the mounting rail and turn the CPU downward until it rests on the mounting rail.

Demounting > Demounting CPU



**6.** Rebind your modules by moving the CPU along with the extension module on the mounting rail.



7. To fix the CPU at the mounting rail, move the locking levers back to the initial position.



**8.** Remove the connectors, which are not necessary at the CPU.



- 9. Plug again the wired connectors.
  - ⇒ Now you can bring your system back into operation.

Demounting > Demounting the extension module

## 2.6.2 Demounting the extension module

1111111

### **Proceeding**

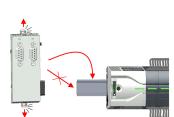
- 1. Power-off your system.
- **2.** Remove the corresponding bus connectors.
- **3.** Use a screwdriver to pull the locking levers of the extension module outwards until these engage audible.



**4.** Remove the extension module from the CPU by sliding it on the mounting rail.



**5.** Remove the extension module with a rotation upwards from the mounting rail.

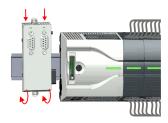


**6.** Pull the locking levers of the extension module outwards until these engage audible.



#### **CAUTION!**

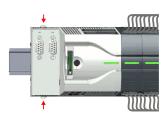
It is not allowed to mount the module sideways on the mounting rail, as otherwise the module may be damaged!



**7.** Plug the extension module from the top onto the mounting rail and turn the extension module downward until it rests on the mounting rail.



**8.** Reattach the extension module to the CPU by sliding the extension module on the mounting rail to the right until the interface connector slightly locks into the CPU.



- **9.** Move the locking levers back to the initial position.
- **10.** Plug the corresponding bus connectors.
  - ⇒ Now you can bring your system back into operation.

Demounting > Demounting periphery module

## 2.6.3 Demounting periphery module

#### Remove connector

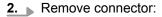
By means of a screwdriver there is the possibility to remove the connectors e.g. for module exchange with a fix wiring. For this each connector has indentations for unlocking at the top. Unlocking takes place by the following proceeding:

**1.** Power-off your system.



#### **CAUTION!**

Make sure that the working contacts from the relay module are disconnected from the power supply!



Insert your screwdriver from above into one of the indentations.



- 3. Push the screwdriver backwards:
  - ⇒ The connector is unlocked and can be removed.



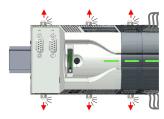
#### **CAUTION!**

Via wrong operation such as pressing the screwdriver downward, the connector may be damaged!

**4.** In this way, remove all plugged connectors on the periphery module.



# Replace the periphery module



- Remove the modules that are connected to the module to be replaced by pulling their release levers outwards until these engage audible ...
- 2. ... and move the modules accordingly.



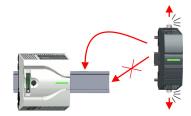
VIPA System MICRO

Basics and mounting

Demounting > Demounting periphery module



**3.** Remove the periphery module with a rotation upwards from the mounting rail.



**4.** Pull the locking levers outwards until these engage audible.

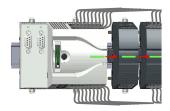


### **CAUTION!**

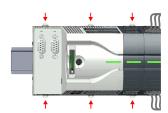
It is not allowed to mount the module sideways on the mounting rail, as otherwise the module may be damaged!



Plug the periphery module from the top onto the mounting rail and turn the periphery module downward until it rests on the mounting rail.



**6.** Reconnect all modules by pushing them together again on the mounting rail.



**7.** Move the locking levers back to the initial position.



**8.** Remove the connectors, which are not necessary.

Demounting > Demounting periphery module



- **9.** Plug again the wired connectors.
  - ⇒ Now you can bring your system back into operation.

Installation guidelines

## 2.7 Installation guidelines

#### General

The installation guidelines contain information about the interference free deployment of a PLC system. There is the description of the ways, interference may occur in your PLC, how you can make sure the electromagnetic compatibility (EMC), and how you manage the isolation.

#### What does EMC mean?

Electromagnetic compatibility (EMC) means the ability of an electrical device, to function error free in an electromagnetic environment without being interfered respectively without interfering the environment.

The components of VIPA are developed for the deployment in industrial environments and meets high demands on the EMC. Nevertheless you should project an EMC planning before installing the components and take conceivable interference causes into account.

# Possible interference causes

Electromagnetic interferences may interfere your control via different ways:

- Electromagnetic fields (RF coupling)
- Magnetic fields with power frequency
- Bus system
- Power supply
- Protected earth conductor

Depending on the spreading medium (lead bound or lead free) and the distance to the interference cause, interferences to your control occur by means of different coupling mechanisms.

#### There are:

- galvanic coupling
- capacitive coupling
- inductive coupling
- radiant coupling

## **Basic rules for EMC**

In the most times it is enough to take care of some elementary rules to guarantee the EMC. Please regard the following basic rules when installing your PLC.

- Take care of a correct area-wide grounding of the inactive metal parts when installing your components.
  - Install a central connection between the ground and the protected earth conductor system.
  - Connect all inactive metal extensive and impedance-low.
  - Please try not to use aluminium parts. Aluminium is easily oxidizing and is therefore less suitable for grounding.
- When cabling, take care of the correct line routing.
  - Organize your cabling in line groups (high voltage, current supply, signal and data lines).
  - Always lay your high voltage lines and signal respectively data lines in separate channels or bundles.
  - Route the signal and data lines as near as possible beside ground areas (e.g. suspension bars, metal rails, tin cabinet).

Installation guidelines

- Proof the correct fixing of the lead isolation.
  - Data lines must be laid isolated.
  - Analog lines must be laid isolated. When transmitting signals with small amplitudes the one sided laying of the isolation may be favourable.
  - Lay the line isolation extensively on an isolation/protected earth conductor rail directly after the cabinet entry and fix the isolation with cable clamps.
  - Make sure that the isolation/protected earth conductor rail is connected impedance-low with the cabinet.
  - Use metallic or metallised plug cases for isolated data lines.
- In special use cases you should appoint special EMC actions.
  - Consider to wire all inductivities with erase links.
  - Please consider luminescent lamps can influence signal lines.
- Create a homogeneous reference potential and ground all electrical operating supplies when possible.
  - Please take care for the targeted employment of the grounding actions. The grounding of the PLC serves for protection and functionality activity.
  - Connect installation parts and cabinets with your PLC in star topology with the isolation/protected earth conductor system. So you avoid ground loops.
  - If there are potential differences between installation parts and cabinets, lay sufficiently dimensioned potential compensation lines.

#### Isolation of conductors

Electrical, magnetically and electromagnetic interference fields are weakened by means of an isolation, one talks of absorption. Via the isolation rail, that is connected conductive with the rack, interference currents are shunt via cable isolation to the ground. Here you have to make sure, that the connection to the protected earth conductor is impedancelow, because otherwise the interference currents may appear as interference cause.

When isolating cables you have to regard the following:

- If possible, use only cables with isolation tangle.
- The hiding power of the isolation should be higher than 80%.
- Normally you should always lay the isolation of cables on both sides. Only by means of the both-sided connection of the isolation you achieve high quality interference suppression in the higher frequency area. Only as exception you may also lay the isolation one-sided. Then you only achieve the absorption of the lower frequencies. A one-sided isolation connection may be convenient, if:
  - the conduction of a potential compensating line is not possible.
  - analog signals (some mV respectively μA) are transferred.
  - foil isolations (static isolations) are used.
- With data lines always use metallic or metallised plugs for serial couplings. Fix the isolation of the data line at the plug rack. Do not lay the isolation on the PIN 1 of the plug bar!
- At stationary operation it is convenient to strip the insulated cable interruption free and lay it on the isolation/protected earth conductor line.
- To fix the isolation tangles use cable clamps out of metal. The clamps must clasp the isolation extensively and have well contact.
- Lay the isolation on an isolation rail directly after the entry of the cable in the cabinet. Lead the isolation further on to your PLC and don't lay it on there again!



#### **CAUTION!**

## Please regard at installation!

At potential differences between the grounding points, there may be a compensation current via the isolation connected at both sides.

Remedy: Potential compensation line

General data

## 2.8 General data

Conformity and approval								
Conformity								
CE	2014/35/EU	Low-voltage directive						
	2014/30/EU	EMC directive						
Approval								
UL	-	Refer to Technical data						
others								
RoHS	2011/65/EU	Restriction of the use of certain hazardous substances in electrical and electronic equipment						

Protection of persons and device protection								
Type of protection	-	IP20						
Electrical isolation								
to the field bus	-	electrically isolated						
to the process level	-	electrically isolated						
Insulation resistance	-	-						
Insulation voltage to reference earth	Insulation voltage to reference earth							
Inputs / outputs	-	AC / DC 50V, test voltage AC 500V						
Protective measures	-	against short circuit						

Environmental conditions to EN 61131-2										
Climatic										
Storage / transport	EN 60068-2-14	-25+70°C								
Operation										
Horizontal installation hanging	EN 61131-2	0+60°C								
Horizontal installation lying	EN 61131-2	0+60°C								
Vertical installation	EN 61131-2	0+60°C								
Air humidity	EN 60068-2-30	RH1 (without condensation, rel. humidity 1095%)								
Pollution	EN 61131-2	Degree of pollution 2								
Installation altitude max.	-	2000m								
Mechanical										
Oscillation	EN 60068-2-6	1g, 9Hz 150Hz								
Shock	EN 60068-2-27	15g, 11ms								

General data

Mounting conditions							
Mounting place	-	In the control cabinet					
Mounting position	-	Horizontal and vertical					

EMC	Standard		Comment
Emitted interference	EN 61000-6-4		Class A (Industrial area)
Noise immunity	EN 61000-6-2		Industrial area
zone B		EN 61000-4-2	ESD
			8kV at air discharge (degree of severity 3),
			4kV at contact discharge (degree of severity 2)
		EN 61000-4-3	HF field immunity (casing)
			80MHz 1000MHz, 10V/m, 80% AM (1kHz)
			1.4GHz 2.0GHz, 3V/m, 80% AM (1kHz)
			2GHz 2.7GHz, 1V/m, 80% AM (1kHz)
		EN 61000-4-6	HF conducted
			150kHz 80MHz, 10V, 80% AM (1kHz)
		EN 61000-4-4	Burst, degree of severity 3
		EN 61000-4-5	Surge, degree of severity 3 *

<sup>\*)</sup> Due to the high-energetic single pulses with Surge an appropriate external protective circuit with lightning protection elements like conductors for lightning and overvoltage is necessary.

VIPA System MICRO Analog input

General

## 3 Analog input

### 3.1 General

### Cables for analog signals

For analog signals you should use screened cables to reduce interference. The cable screening should be grounded at both ends. If there are differences in the potential between the cable ends, there may occur a potential compensating current that could disturb the analog signals. In this case you should ground the cable screening only at one end.

#### **Connecting sensors**

Depending on the module the following sensors may be connected to the analog input modules:

- Current sensor
- Voltage sensor
- Resistance-type sensors
- Temperature sensors



Please take care of the correct polarity when installing the sensors! Please install short circuits at non-used inputs by connecting the positive contact with the channel ground of the according channel.

#### **Parameterization**

The parameterization via CPU, PROFIBUS and PROFINET happens by means of record sets (DS). The corresponding record set number may be found at the respective module description.

### **Diagnostic functions**

The modules have diagnostics capability. The following errors can release a diagnostic:

- Error in parameterization
- Measuring range over-/underflow
- Wire break



## Alternated blinking of the channel error LEDs

The alternate blinking of the channel error LEDs of channel 0 and 1 indicates a watchdog error due to a system overload. Restart with a power cycle your system. If the error occurred again, check configuration and circuit and adjust them if necessary. If the error persists, please contact our support.

Analog input VIPA System MICRO

Analog value

## 3.2 Analog value

# Representation of analog values

Analog values are exclusively processed in a binary format. For this the analog module transforms every process signal into a digital value and transfers this as word. The analog values are displayed as a fixed-point number in the two's complement.

Resolution	Analog value															
	High byte (byte 0)								Low byte (byte 1)							
Bit number	15	5 14 13 12 11 10 9 8						8	7	6	5	4	3	2	1	0
Value	SG	214	2 <sup>13</sup>	2 <sup>12</sup>	2 <sup>11</sup>	2 <sup>10</sup>	29	28	27	2 <sup>6</sup>	<b>2</b> <sup>5</sup>	24	<b>2</b> <sup>3</sup>	22	2 <sup>1</sup>	20
16bit	SG	Measuring value														

## Sign bit (SG)

Here it is essential:

Bit 15 = "0": → positive value
Bit 15 = "1": → negative value

#### Behavior at error

As soon as a measured value exceeds the overdrive region respectively falls below the underdrive region, the following value is issued:

- Measuring value > end of overdrive region: 32767 (7FFFh)
- Measuring value < end of underdrive region:</li>-32768 (8000h)

At a parameterization error the value 32767 (7FFFh) is issued.

VIPA System MICRO Analog input

Measuring ranges and function numbers

## 3.3 Measuring ranges and function numbers

## General

In the following there are the measuring ranges with function number listed, which were supported by the corresponding analog module. The here listed formulas allow you to transform an evaluated measuring value (analog value) to a value assigned to the measuring range (digital value) and vice versa.

## Voltage

### 0 ... 10V

Meas. range	Voltage	Decimal	Hex	Range	Formulas
(funct. no.)	(U)	(D)			
0 10V	11.76V	32511	7EFFh	overrange	D 27649 U
Siemens S7 format	10V	27648	6C00h	nominal range	$D = 27648 \cdot \frac{U}{10}$
(10h)	5V	13824	3600h		
	0V	0	0000h		$U = D \cdot \frac{10}{27648}$
	-1.76V	-4864	ED00h	underrange	2/048
0 10V	12.5V	20480	5000h	overrange	D 16204 U
Siemens S5 format	10V	16384	4000h	nominal range	$D = 16384 \cdot \frac{U}{10}$
(20h)	5V	8192	2000h		
	0V	0	0000h		$U = D \cdot \frac{10}{16384}$
	-2V	-3277	F333h	underrange	16384

## Voltage

### **±10V**

Meas. range	Voltage	Decimal	Hex	Range	Formulas
(funct. no.)	(U)	(D)			
±10V	11.76V	32511	7EFFh	overrange	D 27649
Siemens S7 format	10V	27648	6C00h	nominal range	$D = 27648 \cdot \frac{U}{10}$
(12h)	5V	13824	3600h		10
	0V	0	0000h		$U = D \cdot \frac{10}{27648}$
	-5V	-13824	CA00h		2/040
	-10V	-27648	9400h		
	-11.76V	-32512	8100h	underrange	
±10V	12.5V	20480	5000h	overrange	D 16394 U
Siemens S5 format	10V	16384	4000h	nominal range	$D = 16384 \cdot \frac{U}{10}$
(22h)	5V	8192	2000h		
	0V	0	0000h		$U = D \cdot \frac{10}{16384}$
	-5V	-8192	E000h		16384
	-10V	-16384	C000h		
	-12.5V	-20480	B000h	underrange	

Analog input VIPA System MICRO

Measuring ranges and function numbers

## Voltage

## -80 ... 80mV

Meas. range	Voltage	Decimal	Hex	Range	Formulas
(funct. no.)	(U)	(D)			
-80 80mV	94.07mV	32511	7EFFh	overrange	D 27649 U
Siemens S7 format	80mV	27648	6C00h	nominal range	$D = 27648 \cdot \frac{U}{80}$
(11h)	0V	0	0000h		
	-80mV	-27648	9400h		$U = D \cdot \frac{80}{27648}$
	-94.07mV	-32512	8100h	underrange	27648
-80 80mV	100mV	20480	5000h	overrange	$D = 16384 \cdot \frac{U}{80}$
Siemens S5 format	80mV	16384	4000h	nominal range	$D = 16384 \cdot {80}$
(21h)	0V	0	0000h		
	-80mV	-16384	C000h		$U = D \cdot \frac{80}{16000}$
	-100mV	-20480	B000h	underrange	16384

Measuring ranges and function numbers

### Current

### 0(4) ... 20mA

Meas. range	Current	Decimal	Hex	Range	Formulas
(funct. no.)	(I)	(D)			
0 20mA	23.52mA	32511	7EFFh	overrange	D 27640 I
Siemens	20mA	27648	6C00h	nominal range	$D = 27648 \cdot \frac{I}{20}$
S7 format	10mA	13824	3600h		
(31h)	0mA	0	0000h		$I = D \cdot \frac{20}{27648}$
	-3.52mA	-4864	ED00h	underrange	27648
0 20mA	25.00mA	20480	5000h	overrange	D 16304 I
Siemens	20mA	16384	4000h	nominal range	$D = 16384 \cdot \frac{1}{20}$
S5 format	10mA	8192	2000h		
(41h)	0mA	0	0000h		$I = D \cdot \frac{20}{16384}$
	-4,00mA	-3277	F333h	underrange	
4 20mA	22.81mA	32511	7EFFh	overrange	$D = 27648 \cdot \frac{I-4}{16}$
Siemens	20mA	27648	6C00h	nominal range	16
S7 format	12mA	13824	3600h		$I = D \cdot \frac{16}{27648} + 4$
(30h)	4mA	0	0000h		$T = D \cdot \frac{1}{27648} + 4$
	1.19mA	-4864	ED00h	underrange	
4 20mA	24.00mA	20480	5000h	overrange	$D = 16384 \cdot \frac{I-4}{16}$
Siemens S5 format (40h)	20mA	16384	4000h	nominal range	16
	12mA	8192	2000h		16
	4mA	0	0000h		$I = D \cdot \frac{16}{16384} + 4$
	0.8mA	-3277	F333h	underrange	

### RTD

Measuring range (funct. no.)	Measuring value	Signal range	Range
2 wire: PT100	+1000°C	+10000	overrange
(50h)	-200 +850°C	-2000 +8500	nominal range
	-243°C	-2430	underrange
2 wire: PT1000	+1000°C	+10000	overrange
(51h)	-200 +850°C	-2000 +8500	nominal range
	-243°C	-2430	underrange
2 wire: NI100	+295°C	+2950	overrange
(52h)	-60 +250°C	-600 +2500	nominal range
	-105°C	-1050	underrange

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Measuring range	Measuring value	Signal range	Range
(funct. no.)			
2 wire: NI1000	+295°C	+2950	overrange
(53h)	-60 +250°C	-600 <b>+2</b> 500	nominal range
	-105°C	-1050	underrange
3 wire: PT100	+1000°C	+10000	overrange
(58h)	-200 +850°C	-2000 +8500	nominal range
	-243°C	-2430	underrange
3 wire: PT1000	+1000°C	+10000	overrange
(59h)	-200 +850°C	-2000 +8500	nominal range
	-243°C	-2430	underrange
3 wire: NI100	+295°C	+2950	overrange
(5Ah)	-60 +250°C	-600 <b>+</b> 2500	nominal range
	-105°C	-1050	underrange
3 wire: NI1000	+295°C	+2950	overrange
(5Bh)	-60 +250°C	-600 <b>+</b> 2500	nominal range
	-105°C	-1050	underrange
4 wire: PT100	+1000°C	+10000	overrange
(60h)	-200 +850°C	-2000 +8500	nominal range
	-243°C	-2430	underrange
4 wire: PT1000	+1000°C	+10000	overrange
(61h)	-200 +850°C	-2000 +8500	nominal range
	-243°C	-2430	underrange
4 wire: NI100	+295°C	+2950	overrange
(62h)	-60 +250°C	-600 <b>+</b> 2500	nominal range
	-105°C	-1050	underrange
4 wire: NI1000	+295°C	+2950	overrange
(63h)	-60 +250°C	-600 <b>+</b> 2500	nominal range
	-105°C	-1050	underrange
2 wire: 0 $60\Omega$			overrange
(70h)	0 60Ω	0 32767	nominal range
			underrange
2 wire: 0 $600\Omega$			overrange
(71h)	$0 \dots 600\Omega$	0 32767	nominal range
			underrange
2 wire: 0 3000Ω			overrange
(72h)	0 3000Ω	0 32767	nominal range

Measuring range	Measuring value	Signal range	Range
(funct. no.)			
			underrange
3 wire: 0 $60\Omega$			overrange
(78h)	$0 \dots 60\Omega$	0 32767	nominal range
			underrange
3 wire: 0 $600\Omega$			overrange
(79h)	$0 \dots 600\Omega$	0 32767	nominal range
			underrange
3 wire: 0 3000 $\Omega$			overrange
(7Ah)	$0 \dots 3000\Omega$	0 32767	nominal range
			underrange
4 wire: 0 $60\Omega$			overrange
(80h)	0 60Ω	0 32767	nominal range
			underrange
4 wire: 0 $600\Omega$			overrange
(81h)	$0 \dots 600\Omega$	0 32767	nominal range
			underrange
4 wire: 0 $3000\Omega$			overrange
(82h)	$0 \dots 3000\Omega$	0 32767	nominal range
			underrange
2 wire: 0 $60\Omega$			overrange
(90h)	0 60Ω	0 6000	nominal range
			underrange
2 wire: 0 $600\Omega$			overrange
(91h)	$0 \dots 600\Omega$	0 6000	nominal range
			underrange
2 wire: 0 $3000\Omega$			overrange
(92h)	$0 \dots 3000\Omega$	0 30000	nominal range
			underrange
3 wire: 0 $60\Omega$			overrange
(98h)	$0 \dots 60\Omega$	0 6000	nominal range
			underrange
3 wire: 0 $600\Omega$			overrange
(99h)	$0 \dots 600\Omega$	0 6000	nominal range
			underrange
3 wire: 0 3000Ω			overrange

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Measuring range	Measuring value	Signal range	Range
(funct. no.)			
(9Ah)	$0 \dots 3000\Omega$	0 30000	nominal range
			underrange
4 wire: 0 $60\Omega$			overrange
(A0h)	$0 \dots 60\Omega$	0 6000	nominal range
			underrange
4 wire: 0 $600\Omega$			overrange
(A1h)	$0 \dots 600\Omega$	0 6000	nominal range
			underrange
4 wire: 0 $3000\Omega$			overrange
(A2h)	$0 \dots 3000\Omega$	0 30000	nominal range
			underrange
2 wire: 0 60Ω	$70.55\Omega$	32511	overrange
(D0h)	$0 \dots 60\Omega$	0 27648	nominal range
			underrange
2 wire: 0 $600\Omega$	$705.5\Omega$	32511	overrange
(D1h)	$0 \dots 600\Omega$	0 27648	nominal range
			underrange
2 wire: 0 $3000\Omega$	$3528\Omega$	32511	overrange
(D2h)	$0 \dots 3000\Omega$	0 27648	nominal range
			underrange
3 wire: 0 $60\Omega$	$70.55\Omega$	32511	overrange
(D8h)	$0 \dots 60\Omega$	0 27648	nominal range
			underrange
3 wire: 0 $600\Omega$	$705.5\Omega$	32511	overrange
(D9h)	$0 \dots 600\Omega$	0 27648	nominal range
			underrange
3 wire: 0 $3000\Omega$	$3528\Omega$	32511	overrange
(DAh)	$0 \dots 3000\Omega$	0 27648	nominal range
			underrange
4 wire: 0 $60\Omega$	$70.55\Omega$	32511	overrange
(E0h)	$0 \dots 60\Omega$	0 27648	nominal range
			underrange
4 wire: 0 $600\Omega$	705.5Ω	32511	overrange
(E1h)	$0 \dots 600\Omega$	0 27648	nominal range
			underrange

Measuring range	Measuring value	Signal range	Range
(funct. no.)			
4 wire: 0 $3000\Omega$	$3528\Omega$	32511	overrange
(E2h)	$0 \dots 3000\Omega$	0 27648	nominal range
			underrange

TC Temperature

Measuring range (funct. no.)	Measuring value in °C (0.1°C/digit)	Measuring value in °F (0.1°F/digit)	Measuring value in K (0.1K/digit)	Range
Type J:	+14500	26420	17232	overrange
[Fe-Cu-Ni IEC]	-2100 +12000	-3460 21920	632 14732	nominal range
-210 +1200°C -346 2192°F 63.2 1473.2K (B0h: ext. comp. 0°C) (C0h: int. comp. 0°C)				underrange
Type K:	+16220	29516	18952	overrange
[Ni-Cr-Ni]	-2700 +13720	-4540 25016	0 16452	nominal range
-270 +1372°C -454 2501.6°F 0 1645.2K (B1h: ext. comp. 0°C) (C1h: int. comp. 0°C)		1.2.		underrange
Type N:	+15500	28220	18232	overrange
[Ni-Cr-Si]	-2700 +13000	-4540 23720	0 15732	nominal range
-270 +1300°C -454 2372°F 0 1573.2K (B2h: ext. comp. 0°C) (C2h: int. comp. 0°C)				underrange
Type R:	+20190	32766	22922	overrange
[PtRh-Pt]	-500 <b>+</b> 17690	-580 32162	2232 20422	nominal range
-50 +1769°C -58 3216.2°F 223.2 2042.2K (B3h: ext. comp. 0°C) (C3h: int. comp. 0°C)	-1700	-2740	1032	underrange
Type S:	+20190	32766	22922	overrange

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Measuring range	Measuring value in °C	Measuring value in °F	Measuring value in K	Range
(funct. no.)	(0.1°C/digit)	(0.1°F/digit)	(0.1K/digit)	
[PtRh-Pt]	-500 <b>+</b> 17690	-580 32162	2232 20422	nominal range
-50 +1769°C -58 3216.2°F 223.2 2042.2K (B4h: ext. comp. 0°C) (C4h: int. comp. 0°C)	-1700	-2740	1032	underrange
Type T:	+5400	10040	8132	overrange
[Cu-Cu-Ni]	-2700 +4000	-4540 7520	32 6732	nominal range
-270 +400°C -454 752°F 3.2 673.2K (B5h: ext. comp. 0°C) (C5h: int. comp. 0°C)				underrange
Type B:	+20700	32766	23432	overrange
[PtRh-PtRh]	0 +18200	320 27865	2732 20932	nominal range
0 +1820°C 32 2786.5°F 273.2 2093.2K (B6h: ext. comp. 0°C) (C6h: int. comp. 0°C)	-1200	-1840	1532	underrange
Type C:	+25000	32766	23432	overrange
[WRe5-WRe26]	0 +23150	320 27865	2732 20932	nominal range
0 +2315°C 32 2786.5°F 273.2 2093.2K (B7h: ext. comp. 0°C) (C7h: int. comp. 0°C)	-1200	-1840	1532	underrange
Type E:	+12000	21920	14732	overrange
[Ni-Cr - Cu-Ni ]	-2700 +10000	-4540 18320	0 12732	nominal range
-270 +1000°C -454 1832°F 0 1273.2K (B8h: ext. comp. 0°C) (C8h: int. comp. 0°C)				underrange
Type L: [Fe-Cu-Ni] -200 +900°C -328 1652°F	+11500	21020	14232	overrange

Measuring range (funct. no.)	Measuring value in °C (0.1°C/digit)	Measuring value in °F (0.1°F/digit)	Measuring value in K (0.1K/digit)	Range
73.2 1173.2K	-2000 +9000	-3280 16520	732 11732	nominal range
(B9h: ext. comp. 0°C) (C9h: int. comp. 0°C)	<del></del>		-1-	underrange

M31-1CD50 - AI 4 x 16Bit U, I, RTD, TC

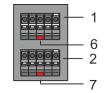
### 3.4 M31-1CD50 - AI 4 x 16Bit U, I, RTD, TC

### **Properties**

The electronic module has 4 inputs for measuring with parameterizable functions. The channels of the module are isolated to the backplane bus.

- 4 analog inputs
- Voltage measuring
  - Suited for sensors with ±10V, 0 ... 10V or ±80mV
- Current measuring
  - Suited for sensors with 0 ... 20mA
  - 4 ... 20mA with external supply
- RTD
  - Suited for resistance-type sensors
    - 0....3000 Ohm: 2, 3 or 4 wire
  - Resistance temperature sensors
     Pt100, Pt1000, NI100, NI1000: 2, 3 or 4 wire
- TC
  - Suited for sensors with type
     Typ J, K, N, R, S, T, B, C, E, L
- Interrupt and diagnostics function
- 16bit resolution

#### **Structure**





- 1 X2: Terminal channel 1
- 2 X1: Terminal channel 0
- 3 Status bar periphery module
- 4 X3: Terminal channel 2
- 5 X4: Terminal channel 3
- 6 X2 AI 1: LED Error channel 1
- 7 X1 Al 0: LED Error channel 08 X3 Al 2: LED Error channel 2
- 9 X4 Al 3: LED Error channel 3

Status bar

LED	Description
	LEDs green on: Backplane bus communication and module status are OK
	LED red on: Module reports an error

M31-1CD50 - Al 4 x 16Bit U, I, RTD, TC

LED	Description
	LED red blinks with 1Hz: Error in configuration
	LEDs green are blinking with 1Hz: Error backplane bus communication

### **LEDs connectors**

Pin		LED	Description
X2	Al Channel 1	red	Error channel x
X1	Al Channel 0	red	Signal leaves measuring range
X3	Al Channel 2	red	<ul><li>Error in parameterization</li><li>Wire break (RTD and TC, if parameterized)</li></ul>
X4	Al Channel 3	red	, , , , , , , , , , , , , , , , , , , ,

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M31-1CD50 - AI 4 x 16Bit U, I, RTD, TC

### Pin assignment

X2: Channe	el 1	Pin 5: RTD	Pin 4: TC	Pin 3: U/I +	Pin 2: -	Pin 1: M1
X2: 5   4   3   U/I +	2 1 M1	-	-	V +	V -	-
	_	-	-	A +	A -	-
TC		-	TC+	-	TC -	-
RTD2		RTD2 +	-	-	-	RTD2 -
		RTD3 +	RTD3 +	-	RTD3 - *	RTD3 -
RTD3		RTD4 +	RTD4 +	-	RTD4 -	RTD4 -
RTD4						
X1: Channe	el O	Pin 5: RTD	Pin 4: TC	Pin 3: U/I +	Pin 2: -	Pin 1: M0
X1: 5 RTD 4 TC 3 U/I +	2 1 M0	-	-	V +	V -	-
		-	-	A +	A -	-
TC		-	TC +	-	TC -	-
RTD2		RTD2 +	-	-	-	RTD2 -
DIDO		RTD3 +	RTD3 +	-	RTD3 - *	RTD3 -
RTD3		RTD4 +	RTD4 +	-	RTD4 -	RTD4 -
RTD4						
X3: Channe	el 2	Pin 1: M2	Pin 2: -	Pin 3: U/I +	Pin 4: TC	Pin 5: RTD
X3: Channe	4 TC 5 RTD	Pin 1: M2 -	<b>Pin 2: -</b>	Pin 3: U/I + V +	Pin 4: TC	Pin 5: RTD
X3: 1  2  3	41 51	Pin 1: M2 - -				
X3: 1 M2 2 - 3 U/I +	41 51	-	V -	V +	-	-
X3: 1	41 51	-	V - A -	V + A +	-	-
X3: 1 M2 2 - 3 U/I + TC	41 51	-	V - A - TC -	V + A +	-	- - -
X3: 1	TC 5 RTD	- - - RTD2 -	V - A - TC -	V + A + -	- - TC + -	- - - RTD2 +
X3: 1	TC 5 RTD	- - - RTD2 - RTD3 -	V - A - TC - - RTD3 - *	V + A + -	- TC + - RTD3 +	- - - RTD2 + RTD3 +
X3: 1	4 TC 5 RTD	- - - RTD2 - RTD3 -	V - A - TC - - RTD3 - *	V + A + -	- TC + - RTD3 +	- - - RTD2 + RTD3 +
X3: 1	4 TC 5 RTD	- - - RTD2 - RTD3 - RTD4 -	V - A - TC - - RTD3 - * RTD4 -	V + A +	- TC + - RTD3 + RTD4 +	- - - RTD2 + RTD3 + RTD4 +
X3: 1	4 TC 5 RTD	- - - RTD2 - RTD3 - RTD4 -	V - A - TC RTD3 - * RTD4 -	V + A + Pin 3: U/I +	- TC + - RTD3 + RTD4 +	- - - RTD2 + RTD3 + RTD4 +
X3: 1	4 TC 5 RTD	- - - RTD2 - RTD3 - RTD4 -	V - A - TC RTD3 - * RTD4 -  Pin 2: - V -	V + A + Pin 3: U/I + V +	- TC + - RTD3 + RTD4 +  Pin 4: TC -	- - - RTD2 + RTD3 + RTD4 +
X3: 1 M2 2 3 U/I + TC RTD2 RTD3  X4: Channe  X4: 1 M3 2 3 U/I +	4 TC 5 RTD	RTD2 - RTD3 - RTD4 -  Pin 1: M3	V - A - TC RTD3 - * RTD4 -  Pin 2: - V - A -	V + A +  Pin 3: U/I + V + A +	- TC + - RTD3 + RTD4 +  Pin 4: TC	
X3: 1 M2 2 3 U/I + TC RTD2 RTD3 RTD4  X4: Channe  X4: 1 M3 2 3 U/I + TC	4 TC 5 RTD	- - RTD2 - RTD3 - RTD4 - Pin 1: M3 - -	V - A - TC RTD3 - * RTD4 -  Pin 2: - V - A - TC -	V + A +  Pin 3: U/I + V + A + -	- TC + - RTD3 + RTD4 +  Pin 4: TC - TC +	RTD2 + RTD3 + RTD4 +  Pin 5: RTD
X3: 1	4 TC 5 RTD		V - A - TC RTD3 - * RTD4 -  Pin 2: - V - A - TC	V + A +  V + V + A +	- TC + - RTD3 + RTD4 +  Pin 4: TC - TC + -	RTD2 + RTD3 + RTD4 +  Pin 5: RTD RTD2 +

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Please take care of the correct polarity when installing the sensors! Please install short circuits at non-used inputs by connecting the positive contact with the channel ground of the according channel.



### 3/4-wire measurement

For 3-wire measurement (RTD3), it is assumed that all 3 wires have the same resistance, while for 4-wire measurement (RTD4), the resistances of the wires are individually measured and taken into account.

### Supplementation to the installation guidelines TC

To avoid variations in temperature within the module, which may affect the accuracy of the temperature measurement, you should consider the following points when assembling:

- The module should be in a static condition, i.e. the temperature should be as constant as possible in the environment of your module. Installation horizontally suspended in the closed switchgear cabinet without forced ventilation.
- The accuracy is reached after approx. 30 minutes after entering the static condition.

#### Input area

Addr.	PIQ	Bytes	Function
+0	AI 0	2	Analog value channel 0
+2	Al 1	2	Analog value channel 1
+4	Al 2	2	Analog value channel 2
+6	Al 3	2	Analog value channel 3

### **Output area**

No byte of the output area is used by the module.

Analog input VIPA System MICRO

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### 3.4.1 Parameter data

DS - Record set for access via CPU, PROFIBUS and PROFINET

Name	Bytes	Function	Default	DS				
DIAG_EN	1	Diagnostics*	00h	00h				
WIBRK_EN	1	Wire break recognition (only RTD and TC)*	00h	00h				
LIMIT_EN	1	Limit value monitoring*	00h	00h				
RES3	1	reserved	00h	00h				
TEMPCNF	1	Temperature system	00h	01h				
SUPR	1	Interference frequency suppression (SFU)	02h	01h				
RES6	1	reserved	00h	01h				
RES7	1	reserved	00h	01h				
CH0FN	1	Function number channel 0	10h	80h				
CH0FO	1	Function option channel 0	02h	80h				
CH0UL	2	Upper limit value channel 0	7FFFh	80h				
CH0LL	2	Lower limit value channel 0	8000h	80h				
CH1FN	1	Function number channel 1	10h	81h				
CH1FO	1	Function option channel 1	02h	81h				
CH1UL	2	Upper limit value channel 1	7FFFh	81h				
CH1LL	2	Lower limit value channel 1	8000h	81h				
CH2FN	1	Function number channel 2	10h	82h				
CH2FO	1	Function option channel 2	02h	82h				
CH2UL	2	Upper limit value channel 2	7FFFh	82h				
CH2LL	2	Lower limit value channel 2	8000h	82h				
CH3FN	1	Function number channel 3	10h	83h				
CH3FO	1	Function option channel 3	02h	83h				
CH3UL	2	Upper limit value channel 3	7FFFh	83h				
CH3LL	2	Lower limit value channel 3	8000h	83h				
* This record set may only be tran	* This record set may only be transferred at STOP state.							

## DIAG\_EN Diagnostic interrupt

Byte	Bit 7 0
0	<ul><li>Diagnostic interrupt</li><li>00h: disabled</li><li>40h: enabled</li></ul>

Here you can enable respectively disable the diagnostic interrupt.

M31-1CD50 - AI 4 x 16Bit U, I, RTD, TC > Parameter data

### WIBRK\_EN Wire-break recognition

Byte	Bit 7 0
0	<ul> <li>Bit 0: Wire-break recognition channel 0 (1: on)</li> <li>Bit 1: Wire-break recognition channel 1 (1: on)</li> <li>Bit 2: Wire-break recognition channel 2 (1: on)</li> <li>Bit 3: Wire-break recognition channel 3 (1: on)</li> <li>Bit 7 4: reserved</li> </ul>



Wire-break recognition is only possible with RTD and TC!



Due to the high sensitivity of the inputs, unused inputs should be deactivated in the parametrization. Due to the high input impedance, open inputs can be influenced by adjacent channels or due to the measuring method during wire break detection. Since the entire measuring range moves in the mV range, open-loop inputs can already cause measuring range overshoots.

### LIMIT\_EN Limit value monitoring

Byte	Bit 7 0
0	<ul> <li>Bit 0: Limit value monitoring channel 0 (1: on)</li> <li>Bit 1: Limit value monitoring channel 1 (1: on)</li> <li>Bit 2: Limit value monitoring channel 2 (1: on)</li> <li>Bit 3: Limit value monitoring channel 3 (1: on)</li> <li>Bit 7 4: reserved</li> </ul>

## **TEMPCNF Temperature system**

Byte	Bit 7 0
0	Temperature system
	■ Bit 0, 1: Channel 0
	■ Bit 2, 3: Channel 1
	■ Bit 4, 5: Channel 2
	■ Bit 6, 7: Channel 3
	– 00: °C
	– 01: °F
	– 10: K

# SUPR Interference frequency suppression (SFU)

Byte	Bit 7 0
0	Interference frequency suppression
	<ul> <li>Bit 0, 1: Channel 0</li> <li>Bit 2, 3: Channel 1</li> <li>Bit 4, 5: Channel 2</li> <li>Bit 6, 7: Channel 3</li> </ul>
	<ul> <li>00: deactivated</li> <li>01: 60Hz</li> <li>10: 50Hz (Default)</li> <li>11: reserved</li> </ul>

M31-1CD50 - AI 4 x 16Bit U, I, RTD, TC > Parameter data



For RTD and TC input channels the deactivation of the interference frequency suppression is not possible! If the channel is deactivated, the SFU default value for this channel is automatically used!

### **CHxFN Function number** channel x

In the following there are the measuring ranges with corresponding function number listed, which were supported by the analog module. The formulas listed here allow you to transform an evaluated measuring value (analog value) to a value assigned to the measuring range (digital value) and vice versa.



With FFh the corresponding channel is deactivated.

### Voltage

0 ... 10V

Meas. range	Voltage	Decimal	Hex	Range	Formulas
(funct. no.)	(U)	(D)			
0 10V	11.76V	32511	7EFFh	overrange	D 27649 U
Siemens S7 format	10V	27648	6C00h	nominal range	$D = 27648 \cdot \frac{U}{10}$
(10h)	5V	13824	3600h		10
	0V	0	0000h		$U = D \cdot \frac{10}{27648}$
	-1.76V	-4864	ED00h	underrange	
0 10V	12.5V	20480	5000h	overrange	$D = 16384 \cdot \frac{U}{10}$
Siemens S5 format	10V	16384	4000h	nominal range	$D = 10384 \cdot \frac{10}{10}$
(20h)	5V	8192	2000h		
	0V	0	0000h		$U = D \cdot \frac{10}{16224}$
	-2V	-3277	F333h	underrange	16384

M31-1CD50 - Al 4 x 16Bit U, I, RTD, TC > Parameter data

### Voltage

### ±10V

Meas. range	Voltage	Decimal	Hex	Range	Formulas
(funct. no.)	(U)	(D)			
±10V	11.76V	32511	7EFFh	overrange	D 27649 U
Siemens S7 format	10V	27648	6C00h	nominal range	$D = 27648 \cdot \frac{U}{10}$
(12h)	5V	13824	3600h		10
	0V	0	0000h		$U = D \cdot \frac{10}{27648}$
	-5V	-13824	CA00h		2/048
	-10V	-27648	9400h		
	-11.76V	-32512	8100h	underrange	
±10V	12.5V	20480	5000h	overrange	D 16204 U
Siemens S5 format	10V	16384	4000h	nominal range	$D = 16384 \cdot \frac{U}{10}$
(22h)	5V	8192	2000h		
	0V	0	0000h		$U = D \cdot \frac{10}{16384}$
	-5V	-8192	E000h		16384
	-10V	-16384	C000h		
	-12.5V	-20480	B000h	underrange	

### Voltage

-80 ... 80mV

Meas. range	Voltage	Decimal	Hex	Range	Formulas
(funct. no.)	(U)	(D)			
-80 80mV	94.07mV	32511	7EFFh	overrange	D 27649 U
Siemens S7 format	80mV	27648	6C00h	nominal range	$D = 27648 \cdot \frac{U}{80}$
(11h)	0V	0	0000h		
	-80mV	-27648	9400h		$U = D \cdot \frac{80}{27648}$
	-94.07mV	-32512	8100h	underrange	2/648
-80 80mV	100mV	20480	5000h	overrange	D 16294 U
Siemens S5 format	80mV	16384	4000h	nominal range	$D = 16384 \cdot \frac{U}{80}$
(21h)	0V	0	0000h		
	-80mV	-16384	C000h		$U = D \cdot \frac{80}{16384}$
	-100mV	-20480	B000h	underrange	16384

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### Current

### 0(4) ... 20mA

Meas. range	Current	Decimal	Hex	Range	Formulas
(funct. no.)	<b>(I)</b>	(D)			
0 20mA	23.52mA	32511	7EFFh	overrange	D 27640 I
Siemens	20mA	27648	6C00h	nominal range	$D = 27648 \cdot \frac{I}{20}$
S7 format	10mA	13824	3600h		
(31h)	0mA	0	0000h		$I = D \cdot \frac{20}{27648}$
	-3.52mA	-4864	ED00h	underrange	27648
0 20mA	25.00mA	20480	5000h	overrange	D 16204 I
Siemens	20mA	16384	4000h	nominal range	$D = 16384 \cdot \frac{I}{20}$
S5 format	10mA	8192	2000h		
(41h)	0mA	0	0000h		$I = D \cdot \frac{20}{16384}$
	-4,00mA	-3277	F333h	underrange	16384
4 20mA	22.81mA	32511	7EFFh	overrange	$D = 27648 \cdot \frac{I-4}{16}$
Siemens	20mA	27648	6C00h	nominal range	16
S7 format	12mA	13824	3600h		16
(30h)	4mA	0	0000h		$I = D \cdot \frac{16}{27648} + 4$
	1.19mA	-4864	ED00h	underrange	
4 20mA	24.00mA	20480	5000h	overrange	$D = 16384 \cdot \frac{I-4}{16}$
Siemens	20mA	16384	4000h	nominal range	16
S5 format	12mA	8192	2000h		16
(40h)	4mA	0	0000h		$I = D \cdot \frac{16}{16384} + 4$
	0.8mA	-3277	F333h	underrange	

### RTD

Measuring range (funct. no.)	Measuring value	Signal range	Range
2 wire: PT100	+1000°C	+10000	overrange
(50h)	-200 +850°C	-2000 +8500	nominal range
	-243°C	-2430	underrange
2 wire: PT1000	+1000°C	+10000	overrange
(51h)	-200 +850°C	-2000 +8500	nominal range
	-243°C	-2430	underrange
2 wire: NI100	+295°C	+2950	overrange
(52h)	-60 +250°C	-600 +2500	nominal range
	-105°C	-1050	underrange

Measuring range	Measuring value	Signal range	Range
(funct. no.)			
2 wire: NI1000	+295°C	+2950	overrange
(53h)	-60 +250°C	-600 <b>+</b> 2500	nominal range
	-105°C	-1050	underrange
3 wire: PT100	+1000°C	+10000	overrange
(58h)	-200 +850°C	-2000 +8500	nominal range
	-243°C	-2430	underrange
3 wire: PT1000	+1000°C	+10000	overrange
(59h)	-200 +850°C	-2000 +8500	nominal range
	-243°C	-2430	underrange
3 wire: NI100	+295°C	+2950	overrange
(5Ah)	-60 +250°C	-600 +2500	nominal range
	-105°C	-1050	underrange
3 wire: NI1000	+295°C	+2950	overrange
(5Bh)	-60 +250°C	-600 +2500	nominal range
	-105°C	-1050	underrange
4 wire: PT100	+1000°C	+10000	overrange
(60h)	-200 +850°C	-2000 +8500	nominal range
	-243°C	-2430	underrange
4 wire: PT1000	+1000°C	+10000	overrange
(61h)	-200 +850°C	-2000 +8500	nominal range
	-243°C	-2430	underrange
4 wire: NI100	+295°C	+2950	overrange
(62h)	-60 +250°C	-600 <b>+</b> 2500	nominal range
	-105°C	-1050	underrange
4 wire: NI1000	+295°C	+2950	overrange
(63h)	-60 +250°C	-600 <b>+</b> 2500	nominal range
	-105°C	-1050	underrange
2 wire: 0 60Ω			overrange
(70h)	0 60Ω	0 32767	nominal range
			underrange
2 wire: 0 $600\Omega$			overrange
(71h)	$0 \dots 600\Omega$	0 32767	nominal range
			underrange
2 wire: 0 $3000\Omega$			overrange
(72h)	$0 \dots 3000\Omega$	0 32767	nominal range

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Measuring range	Measuring value	Signal range	Range
(funct. no.)			
			underrange
3 wire: 0 60Ω			overrange
(78h)	0 60Ω	0 32767	nominal range
			underrange
3 wire: 0 $600\Omega$			overrange
(79h)	$0 \dots 600\Omega$	0 32767	nominal range
			underrange
3 wire: 0 3000 $\Omega$			overrange
(7Ah)	$0 \dots 3000\Omega$	0 32767	nominal range
			underrange
4 wire: 0 60Ω			overrange
(80h)	0 60Ω	0 32767	nominal range
			underrange
4 wire: 0 $600\Omega$			overrange
(81h)	$0 \dots 600\Omega$	0 32767	nominal range
			underrange
4 wire: 0 $3000\Omega$			overrange
(82h)	$0 \dots 3000\Omega$	0 32767	nominal range
			underrange
2 wire: 0 60Ω			overrange
(90h)	0 60Ω	0 6000	nominal range
			underrange
2 wire: 0 $600\Omega$			overrange
(91h)	$0 \dots 600\Omega$	0 6000	nominal range
			underrange
2 wire: 0 $3000\Omega$			overrange
(92h)	$0 \dots 3000\Omega$	0 30000	nominal range
			underrange
3 wire: 0 60Ω			overrange
(98h)	$0 \dots 60\Omega$	0 6000	nominal range
			underrange
3 wire: 0 $600\Omega$			overrange
(99h)	$0 \dots 600\Omega$	0 6000	nominal range
			underrange
3 wire: 0 3000 $\Omega$			overrange

Measuring range	Measuring value	Signal range	Range
(funct. no.)			
(9Ah)	$0 \dots 3000\Omega$	0 30000	nominal range
			underrange
4 wire: 0 $60\Omega$			overrange
(A0h)	$0 \dots 60\Omega$	0 6000	nominal range
			underrange
4 wire: 0 $600\Omega$			overrange
(A1h)	$0 \dots 600\Omega$	0 6000	nominal range
			underrange
4 wire: 0 $3000\Omega$			overrange
(A2h)	$0 \dots 3000\Omega$	0 30000	nominal range
			underrange
2 wire: 0 60Ω	$70.55\Omega$	32511	overrange
(D0h)	$0 \dots 60\Omega$	0 27648	nominal range
			underrange
2 wire: 0 $600\Omega$	$705.5\Omega$	32511	overrange
(D1h)	$0 \dots 600\Omega$	0 27648	nominal range
			underrange
2 wire: 0 $3000\Omega$	$3528\Omega$	32511	overrange
(D2h)	$0 \dots 3000\Omega$	0 27648	nominal range
			underrange
3 wire: 0 $60\Omega$	$70.55\Omega$	32511	overrange
(D8h)	$0 \dots 60\Omega$	0 27648	nominal range
			underrange
3 wire: 0 $600\Omega$	$705.5\Omega$	32511	overrange
(D9h)	$0 \dots 600\Omega$	0 27648	nominal range
			underrange
3 wire: 0 $3000\Omega$	$3528\Omega$	32511	overrange
(DAh)	$0 \dots 3000\Omega$	0 27648	nominal range
			underrange
4 wire: 0 $60\Omega$	$70.55\Omega$	32511	overrange
(E0h)	$0 \dots 60\Omega$	0 27648	nominal range
			underrange
4 wire: 0 $600\Omega$	705.5Ω	32511	overrange
(E1h)	$0 \dots 600\Omega$	0 27648	nominal range
			underrange

VIPA System MICRO

M31-1CD50 - Al 4 x 16Bit U, I, RTD, TC > Parameter data

Measuring range	Measuring value	Signal range	Range
(funct. no.)			
4 wire: 0 $3000\Omega$	$3528\Omega$	32511	overrange
(E2h)	$0 \dots 3000\Omega$	0 27648	nominal range
			underrange

### TC Temperature

Measuring range (funct. no.)	Measuring value in °C (0.1°C/digit)	Measuring value in °F (0.1°F/digit)	Measuring value in K (0.1K/digit)	Range
Type J:	+14500	26420	17232	overrange
[Fe-Cu-Ni IEC]	-2100 +12000	-3460 21920	632 14732	nominal range
-210 +1200°C -346 2192°F 63.2 1473.2K (B0h: ext. comp. 0°C) (C0h: int. comp. 0°C)				underrange
Type K:	+16220	29516	18952	overrange
[Ni-Cr-Ni]	-2700 +13720	-4540 25016	0 16452	nominal range
-270 +1372°C -454 2501.6°F 0 1645.2K (B1h: ext. comp. 0°C) (C1h: int. comp. 0°C)	<u></u>	<del></del>		underrange
Type N:	+15500	28220	18232	overrange
[Ni-Cr-Si]	-2700 +13000	-4540 23720	0 15732	nominal range
-270 +1300°C -454 2372°F 0 1573.2K (B2h: ext. comp. 0°C) (C2h: int. comp. 0°C)				underrange
Type R:	+20190	32766	22922	overrange
[PtRh-Pt]	-500 +17690	-580 32162	2232 20422	nominal range
-50 +1769°C -58 3216.2°F 223.2 2042.2K (B3h: ext. comp. 0°C) (C3h: int. comp. 0°C)	-1700	-2740	1032	underrange
Type S:	+20190	32766	22922	overrange

Measuring range (funct. no.)	Measuring value in °C	Measuring value in °F	Measuring value in K (0.1K/digit)	Range
	(0.1°C/digit)	(0.1°F/digit)		
[PtRh-Pt]	-500 <b>+</b> 17690	-580 32162	2232 20422	nominal range
-50 +1769°C -58 3216.2°F 223.2 2042.2K (B4h: ext. comp. 0°C) (C4h: int. comp. 0°C)	-1700	-2740	1032	underrange
Type T:	+5400	10040	8132	overrange
[Cu-Cu-Ni]	-2700 +4000	-4540 7520	32 6732	nominal range
-270 +400°C -454 752°F 3.2 673.2K (B5h: ext. comp. 0°C) (C5h: int. comp. 0°C)	<del></del>			underrange
Type B:	+20700	32766	23432	overrange
[PtRh-PtRh]	0 +18200	320 27865	2732 20932	nominal range
0 +1820°C 32 2786.5°F 273.2 2093.2K (B6h: ext. comp. 0°C) (C6h: int. comp. 0°C)	-1200	-1840	1532	underrange
Type C:	+25000	32766	23432	overrange
[WRe5-WRe26]	0 +23150	320 27865	2732 20932	nominal range
0 +2315°C 32 2786.5°F 273.2 2093.2K (B7h: ext. comp. 0°C) (C7h: int. comp. 0°C)	-1200	-1840	1532	underrange
Type E:	+12000	21920	14732	overrange
[Ni-Cr - Cu-Ni ]	-2700 +10000	-4540 18320	0 12732	nominal range
-270 +1000°C -454 1832°F 0 1273.2K (B8h: ext. comp. 0°C) (C8h: int. comp. 0°C)				underrange
Type L: [Fe-Cu-Ni] -200 +900°C -328 1652°F	+11500	21020	14232	overrange

Analog input VIPA System MICRO

M31-1CD50 - AI 4 x 16Bit U, I, RTD, TC > Parameter data

Measuring range (funct. no.)	Measuring value in °C (0.1°C/digit)	Measuring value in °F (0.1°F/digit)	Measuring value in K (0.1K/digit)	Range
73.2 1173.2K	-2000 +9000	-3280 16520	732 11732	nominal range
(B9h: ext. comp. 0°C) (C9h: int. comp. 0°C)				underrange

### CHxFO Function option channel x

Depending on the Interference frequency suppression for each channel the transducer velocity may be set.

Code	Measuring range Velocity (in ms) / channel at interference frequency suppres		
		50Hz	60Hz
	U/I	30 (16bit)	30 (16bit)
01h <sup>2</sup>	RTD / TC	200 (16bit)	200 (16bit)
02h <sup>1, 2</sup>	±80mV	100 (16bit)	100 (16bit)
03h		<del>-</del>	40 (16bit)
04h		-	34 (16bit)
05h		-	20 (15bit)
06h		-	17 (14bit)
07h		-	10 (13bit)

<sup>1)</sup> Default

### CHxUL / CHxLL Channel x

For each channel an *upper* and a *lower limit* may be defined. By presetting 7FFFh for the upper respectively 8000h for the lower limit value the corresponding limit is deactivated. If an adjusted limit value is outside the allowed range, no process interrupt is initialized, but the limit will never be reached.

<sup>2)</sup> For Code 01h and 02h the tolerances of the technical data "with interference frequency suppression" are valid.

M31-1CD50 - AI 4 x 16Bit U, I, RTD, TC > Diagnostics and interrupt

### 3.4.2 Diagnostics and interrupt

Event	Process interrupt	Diagnostics interrupt	parameterizable
Error in project engineering/param.	-	X	-
Wire break (only RTD and TC)	-	X	X
Measuring range overflow	-	X	-
Measuring range underflow	-	X	-
Limit overflow	X	-	X
Limit underflow	X	-	X
Diagnostic buffer overflow	-	X	-
Communication error	-	X	-
Process interrupt lost	+	X	-

### **Process interrupt**

So you may react to asynchronous events, there is the possibility to activate a process interrupt. A process interrupt interrupts the linear program sequence and jumps depending on the master system to a corresponding Interrupt routine. Here you can react to the process interrupt accordingly.

Operating with CPU, PROFIBUS and PROFINET the process interrupt data were transferred via diagnostics telegram.

Name	Bytes	Function	Default
PRIT_OL	1	Limit overflow channel x	00h
PRIT_UL	1	Limit underflow channel x	00h
PRIT_US	2	µs-Ticker	00h

### PRIT\_OL Limit overflow

Byte	Bit 7 0
0	<ul> <li>Bit 0: Limit overflow channel 0</li> <li>Bit 1: Limit overflow channel 1</li> <li>Bit 2: Limit overflow channel 2</li> <li>Bit 3: Limit overflow channel 3</li> <li>Bit 7 4: reserved</li> </ul>

### PRIT\_UL Limit underflow

Byte	Bit 7 0
0	<ul> <li>Bit 0: Limit underflow channel 0</li> <li>Bit 1: Limit underflow channel 1</li> <li>Bit 2: Limit underflow channel 2</li> <li>Bit 3: Limit underflow channel 3</li> <li>Bit 7 4: reserved</li> </ul>

Analog input VIPA System MICRO

M31-1CD50 - Al 4 x 16Bit U, I, RTD, TC > Diagnostics and interrupt

### PRIT\_US µs ticker

Byte	Bit 7 0
0 1	16bit µs value at the moment of the interrupt

μs ticker

In the module there is a 32 bit timer ( $\mu$ s ticker). With PowerON the timer starts counting with 0. After  $2^{32}$ -1 $\mu$ s the timer starts with 0 again. PRIT\_US represents the lower 2 byte of the  $\mu$ s ticker value (0 ...  $2^{16}$ -1).

### Diagnostic data

The diagnostics data serves information about this module. On error the corresponding channel LED of the module is activated and the error is registered in the diagnostics data.

The following errors are listed in the diagnostics data:

- Error in project engineering / parameterization
- Wire-break only RTD and TC (if parameterized)
- External auxiliary supply missing

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

Name	Bytes	Function	Default	DS
ERR_A	1	Diagnostic	00h	01h
MODTYP	1	Module information	15h	
RES2	1	reserved	00h	
ERR_D	1	Diagnostic	00h	
CHTYP	1	Channel type	71h	
NUMBIT	1	Number diagnostic bits per channel	08h	
NUMCH	1	Number of channels of a module	02h	
CHERR	1	Channel error	00h	
CH0ERR	1	Channel-specific error channel 0	00h	
CH1ERR	1	Channel-specific error channel 1	00h	
CH2ERR	1	Channel-specific error channel 2	00h	
CH3ERR	1	Channel-specific error channel 3	00h	
CH4ERR CH7ERR	4	reserved	00h	
DIAG_US	4	μs ticker	00h	

### ERR\_A Diagnostic

Byte	Bit 7 0
0	<ul> <li>Bit 0: set at module failure</li> <li>Bit 1: set at internal error</li> <li>Bit 2: set at external error</li> <li>Bit 3: set at channel error</li> <li>Bit 6 4: reserved</li> <li>Bit 7: set at error in parameterization</li> </ul>

M31-1CD50 - Al 4 x 16Bit U, I, RTD, TC > Diagnostics and interrupt

### **MODTYP Module informa-**

Byte	Bit 7 0
0	<ul> <li>Bit 3 0: module class</li> <li>0101b: Analog module</li> <li>Bit 4: Channel information available</li> <li>Bit 7 5: reserved</li> </ul>

### ERR\_D Diagnostic

Byte	Bit 7 0		
0	<ul> <li>Bit 3 0: reserved</li> <li>Bit 4: set at internal communication error</li> <li>Bit 5: reserved</li> <li>Bit 6: process interrupt lost</li> <li>Bit 7: reserved</li> </ul>		

### **CHTYP Channel type**

Byte	Bit 7 0
0	■ Bit 6 0: Channel type  – 71h: Analog input  ■ Bit 7: reserved

### **NUMBIT Diagnostic bits**

Byte	Bit 7 0
0	Number of diagnostic bits per channel (here 08h)

### **NUMCH Channels**

Byte	Bit 7 0
0	Number of channels of the module (here 04h)

### **CHERR Channel error**

Byte	Bit 7 0
0	<ul> <li>Bit 0: set at error in channel group 0</li> <li>Bit 1: set at error in channel group 1</li> <li>Bit 2: set at error in channel group 2</li> <li>Bit 3: set at error in channel group 3</li> <li>Bit 7 4: reserved</li> </ul>

### **CHxERR Channel-specific**

Byte	Bit 7 0		
0	Channel-specific error: Channel x:		
	■ Bit 0: set at project engineering/parameterization error		
	■ Bit 3 1: reserved		
	■ Bit 4: set at wire break (only RTD and TC)		
	■ Bit 5: set at process interrupt lost		
	■ Bit 6: set at measuring range underflow		
	■ Bit 7: set at measuring range overflow		

Analog input VIPA System MICRO

M31-1CD50 - AI 4 x 16Bit U, I, RTD, TC > Diagnostics and interrupt

### DIAG\_US μs ticker

Byte	Bit 7 0	
03	Value of the µs ticker at the moment of the diagnostic	
	■ In the System MICRO module there is a timer (µs ticker). With PowerON the timer starts counting with 0. After 2 <sup>32</sup> -1µs the timer starts with 0 again.	

M31-1CD50 - Al 4 x 16Bit U, I, RTD, TC > Technical data

### 3.4.3 Technical data

Order no.	M31-1CD50
Туре	SM M31
Module ID	0417 1544
Current consumption/power loss	
Current consumption from backplane bus	150 mA
Power loss	750 mW
Technical data analog inputs	
Number of inputs	4
Cable length, shielded	200 m
Rated load voltage	-
Current consumption from load voltage L+ (without load)	-
Voltage inputs	✓
Min. input resistance (voltage range)	100 kΩ
Input voltage ranges	0 V +10 V
	-10 V +10 V
	-80 mV +80 mV
Operational limit of voltage ranges	+/-0.3%
Operational limit of voltage ranges with SFU	+/-0.3%
Basic error limit voltage ranges	+/-0.2%
Basic error limit voltage ranges with SFU	+/-0.2%
Destruction limit voltage	max. 30V
Current inputs	✓
Max. input resistance (current range)	70 Ω
Input current ranges	0 mA +20 mA
	+4 mA +20 mA
Operational limit of current ranges	+/-0.3%
Operational limit of current ranges with SFU	+/-0.3%
Basic error limit current ranges	+/-0.2%
Radical error limit current ranges with SFU	+/-0.2%
Destruction limit current inputs (voltage)	max. 30V
Destruction limit current inputs (electrical current)	max. 60mA
Resistance inputs	✓
Resistance ranges	0 60 Ohm
	0 600 Ohm
	0 3000 Ohm
Operational limit of resistor ranges	+/-0.3%

VIPA System MICRO

M31-1CD50 - Al 4 x 16Bit U, I, RTD, TC > Technical data

Order no.	M31-1CD50			
Operational limit of resistor ranges with SFU	+/-0.3%			
Basic error limit	+/-0.2%			
Basic error limit with SFU	+/-0.2%			
Destruction limit resistance inputs	max. 30V			
Resistance thermometer inputs	✓			
Resistance thermometer ranges	Pt100			
	Pt1000			
	Ni100			
	Ni1000			
Operational limit of resistance thermometer ranges	+/-0.3%			
Operational limit of resistance thermometer ranges with SFU	+/-0.3%			
Basic error limit thermoresistor ranges	+/-0.2%			
Basic error limit thermoresistor ranges with SFU	+/-0.2%			
Destruction limit resistance thermometer inputs	max. 30V			
Thermocouple inputs	✓			
Thermocouple ranges	type J			
	type L			
	type K			
	type N			
	type R			
	type S			
	type B			
	type C			
	type E			
On analism at lineit of the arrange and a reason	type T			
Operational limit of thermocouple ranges	for type B: +/-14.6K;			
	for type K, Typ N: +/-10.0K; for type S, Typ R: +/-14.1K;			
	for type T: +/-12.0K;			
	for type C: +/-14.0K;			
	for type E: +/-13.0K;			
	for type J: +/-11.0K;			
	for type L: +/-13.5K			
	• •			

M31-1CD50 - Al 4 x 16Bit U, I, RTD, TC > Technical data

Order no.	M31-1CD50
Operational limit of thermocouple ranges with SFU	for type B: +/-14.6K;
	for type K, Typ N: +/-10.0K;
	for type S, Typ R: +/-14.1K;
	for type T: +/-12.0K;
	for type C: +/-14.0K;
	for type E: +/-13.0K;
	for type J: +/-11.0K;
	for type L: +/-13.5K
Basic error limit thermoelement ranges	for type B: +/-14.6K;
	for type K, Typ N: +/-10.0K;
	for type S, Typ R: +/-14.1K;
	for type T: +/-12.0K;
	for type C: +/-14.0K;
	for type E: +/-13.0K;
	for type J: +/-11.0K;
	for type L: +/-13.5K
Basic error limit thermoelement ranges with SFU	for type B: +/-14.6K;
	for type K, Typ N: +/-10.0K;
	for type S, Typ R: +/-14.1K; for type T: +/-12.0K;
	for type C: +/-14.0K;
	for type E: +/-13.0K;
	for type J: +/-11.0K;
	for type L: +/-13.5K
Destruction limit thermocouple inputs	max. 30V
Programmable temperature compensation	-
External temperature compensation	-
Internal temperature compensation	✓
Temperature error internal compensation	8 K
Technical unit of temperature measurement	°C, °F, K
Resolution in bit	16
Measurement principle	Sigma-Delta
Basic conversion time	10ms 200ms (for R/RTD & TC)
Noise suppression for frequency	>80dB (UCM <3,2V)
Status information, alarms, diagnostics	
Status display	Bicolour green/red LED
Interrupts	yes, parameterizable
Process alarm	yes, parameterizable

VIPA System MICRO

M31-1CD50 - Al 4 x 16Bit U, I, RTD, TC > Technical data

Order no.	M31-1CD50			
Diagnostic interrupt	yes, parameterizable			
Diagnostic functions	yes, parameterizable			
Diagnostics information read-out	possible			
Module state	none			
Module error display	Bicolour green/red LED			
Channel error display	red LED per channel			
Isolation				
Between channels	✓			
Between channels of groups to	-			
Between channels and backplane bus	✓			
Between channels and power supply	-			
Max. potential difference between circuits	-			
Max. potential difference between inputs (Ucm)	DC 3 V			
Max. potential difference between Mana and Mintern (Uiso)	DC 75 V/ AC 50 V			
Max. potential difference between inputs and Mana (Ucm)	-			
Max. potential difference between inputs and Mintern (Uiso)	-			
Max. potential difference between Mintern and outputs	-			
Insulation tested with	-			
Datasizes				
Input bytes	8			
Output bytes	0			
Parameter bytes	32			
Diagnostic bytes	20			
Housing				
Material	PPE / PPE GF10			
Mounting	Profile rail 35 mm			
Mechanical data				
Dimensions (WxHxD)	26 mm x 88 mm x 71 mm			
Net weight	88 g			
Weight including accessories	88 g			
Gross weight	105 g			
Environmental conditions				
Operating temperature	0 °C to 60 °C			
Storage temperature	-40 °C to 70 °C			
Certifications				

M31-1CD50 - Al 4 x 16Bit U, I, RTD, TC > Technical data

Order no.	M31-1CD50
UL certification	in preparation
KC certification	in preparation

### Information on error limits

The indicated error limits are valid starting from the following temperatures:

- Thermoelement type L: -100 °C
- Thermoelement type T: -90 °C
- Thermoelement type K: -60 °C
- Thermoelement type B: +70 °C
- Thermoelement type N: -80 °C
- Thermoelement type E: -150 °C
- Thermoelement type R: +200 °C
- Thermoelement type S: +100 °C
- Thermoelement type J: -140 °C

Analog output VIPA System MICRO

General

### 4 Analog output

#### 4.1 General

### Cabling for analog signals

You must only use screened cable when you are connecting analog signals. These cables reduce the effect of electrical interference. The screen of the analog signal cable should be grounded at both ends. In situations with different electrical potentials, it is possible that a current will flow to equalize the potential difference. This current could interfere with the analog signals. Under these circumstances it is advisable to ground the screen of the signal cable at one end only.

### Connecting loads and actuators

You can use the analog output modules to supply loads and actuators with current or voltage.



Please take always care of the correct polarity when connecting actuators! Please leave the output clamps of not used channels disconnected and set the output type of the channel to "deactivated" in the hardware configurator from Siemens.

#### **Parameterization**

The parameterization via CPU, PROFIBUS and PROFINET happens by means of record sets (DS). The corresponding record set number may be found at the respective module description.

### **Diagnostic functions**

The modules have diagnostics capability. The following errors may release a diagnostic:

- Error in parameterization
- Short-circuit recognition
- Wire-break recognition



### Alternated blinking of the channel error LEDs

The alternate blinking of the channel error LEDs of channel 0 and 1 indicates a watchdog error due to a system overload. Restart with a power cycle your system. If the error occurred again, check configuration and circuit and adjust them if necessary. If the error persists, please contact our support.

Output ranges and function numbers

### 4.2 Analog value

### Analog value representation

The analog values are only processed in binary representation. Hereby the binary word variable is transformed into an analog process signal and put out via the corresponding channel. The analog values are displayed as a fixed-point number in the two's complement.

Resolu- tion		Analog value - twos complement														
	High byte (byte 0)									Low byte	e (byte	1)				
Bit number	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Value	SG	214	2 <sup>13</sup>	212	211	2 <sup>10</sup>	<b>2</b> <sup>9</sup>	<b>2</b> <sup>8</sup>	27	2 <sup>6</sup>	<b>2</b> <sup>5</sup>	24	<b>2</b> <sup>3</sup>	<b>2</b> <sup>2</sup>	21	20
15Bit+SG	SG							Ana	alog val	ue (word	i)					

### Sign bit (SG)

The algebraic sign bit is represented by Bit 15. Here it is essential:

■ Bit 15 = "0":  $\rightarrow$  positive value

■ Bit 15 = "1": → negative value

### 4.3 Output ranges and function numbers

#### General

In the following there are the output ranges listed with function number, which were supported by the corresponding analog module. The here listed formulas allow you to transform a value (digital value) to an analog value and vice versa.

### Voltage

### 0 ... 10V

Output range	Voltage	Decimal	Hex	Range	Formulas
(funct. no.)	(U)	(D)			
0 10V	11,76V	32511	7EFFh	overrange	$U = D \times 10$
Siemens	10V	27648	6C00h	nominal range	$U = D x \frac{10}{27648}$
S7 format	5V	13824	3600h		17
(10h)	0V	0	0000h		$D = 27648 \ x \ \frac{U}{10}$
	Not possible, is lir	mited to 0V.		underrange	
0 10V	12,5V	20480	5000h	overrange	$U = D \times \frac{10}{16384}$
Siemens	10V	16384	4000h	nominal range	$C = D \times \frac{16384}{}$
S5 format (20h)	5V	8192	2000h		17
	0V	0	0000h		$D = 16384 \ x \ \frac{U}{10}$
	Not possible, is lir	mited to 0V.		underrange	

Analog output VIPA System MICRO

Output ranges and function numbers

### ±10V

Output range (funct. no.)	Voltage (U)	Decimal (D)	Hex	Range	Formulas
±10V	11.76V	32511	7EFFh	overrange	10
Siemens S format	10V	27648	6C00h	nominal range	$U = D x \frac{10}{27648}$
(12h)	5V	13824	3600h		11
	0V	0	0000h		$D = 27648 \ x \ \frac{U}{10}$
	-5V	-13824	CA00h		
	-10V	-27648	9400h		
	-11.76V	-32512	8100h	underrange	
±10V	12.5V	20480	5000h	overrange	U = D × 10
Siemens S5 format	10V	16384	4000h	nominal range	$U = D x \frac{10}{16384}$
(22h)	5V	8192	2000h		II.
	0V	0	0000h		$D = 16384 \ x \ \frac{U}{10}$
	-5V	-8192	E000h		
	-10V	-16384	C000h		
	-12.5V	-20480	B000h	underrange	

### Current

### 0 ... 20mA

Output range	Current	Decimal	Hex	Range	Formulas
(funct. no.)	<b>(I)</b>	(D)			
0 20mA	23.52mA	32511	7EFFh	overrange	20
Siemens	20mA	27648	6C00h	nominal range	$I = D x \frac{20}{27648}$
S7 format	10mA	13824	3600h		
(31h)	0mA	0	0000h		$D = 27648 \ x \ \frac{I}{20}$
	Not possible, is lin	mited to 0mA.		underrange	20
0 20mA	25.00mA	20480	5000h	overrange	20
Siemens	20mA	16384	4000h	nominal range	$I = D x \frac{20}{16384}$
S5 format	10mA	8192	2000h		
(41h)	0mA	0	0000h		$D = 16384 \times \frac{I}{20}$
	Not possible, is lin	mited to 0mA.		underrange	20

Output ranges and function numbers

### 4 ... 20mA

Output range	Current	Decimal	Hex	Range	Formulas
(funct. no.)	<b>(I)</b>	(D)			
4 20mA	22.81mA	32511	7EFFh	overrange	$I = D \ x \ \frac{16}{27648} + 4$
Siemens	20mA	27648	6C00h	nominal range	27648 + 4
S7 format	12mA	13824	3600h		I-4
(30h)	4mA	0	0000h	D = 27	$D = 27648 \ x \ \frac{I-4}{16}$
	0mA	-6912	E500h	underrange	
4 20mA	24.00mA	20480	5000h	overrange	$I = D \times \frac{16}{16384} + 4$
Siemens	20mA	16384	4000h	nominal range	1 = B x 16384 + 4
S5 format	12mA	8192	2000h		I-4
(40h)	4mA	0	0000h		$D = 16384 \ x \ \frac{I-4}{16}$
	0mA	-4096	F000h	underrange	

VIPA System MICRO **Analog output** 

M32-1BD40 - AO 4 x 12Bit I

### 4.4 M32-1BD40 - AO 4 x 12Bit I

### **Properties**

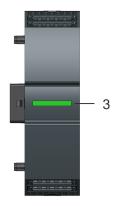
The Analog module has 4 outputs with parameterizable functions. The channels of the module are electrically isolated from the backplane bus. In addition, the channels are isolated to the DC 24V power supply by means of DC/DC converter.

- 4 analog outputs
- Suited for sensors with 0...20mA; 4...20mA
- Diagnostics function
- 12bit resolution

#### **Structure**



- X2: Terminal (DC 24V)
- 2 X1: Terminal (AO 0, AO 1)
- Status bar periphery module
- X3: Terminal (AO 2, AO 3) 4
- 5 X4: Terminal (Shield)
- 6 X2 1L+: LED DC 24V electronic section supply
- 7 X1 AO 0, AO 1: LED channel error
- X3 AO 2, AO 3: LED channel error





### Status bar

LED	Description
	LEDs green on: Backplane bus communication and module status are OK
	LED red on: Module reports an error
	LED red blinks with 1Hz: Error in configuration
	LEDs green are blinking with 1Hz: Error backplane bus communication

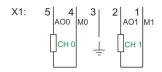
M32-1BD40 - AO 4 x 12Bit I

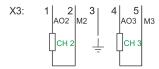
#### **LEDs** connectors

Pin	Function	LED	Description
X2:5	L+	green	DC 24V electronic section supply OK
X1:5	AO 0	red	Error channel x
X1:2	AO 1	red	Error in parameterization
X3:1	AO 2	red	Wire break (if parameterized)
X3:4	AO 3	red	

## Pin assignment







	D'	Forestion	<b>T</b>	LED	December 1
	Pin	Function	Туре	LED	Description
X2:	1	Ŧ	0		Shield
	2	<u> </u>	0		Shield
	3	Ť	I		Shield
	4	M	I		Ground power supply (M)
	5	L+	I	green	Power supply DC 24V (L+)
X1:	1	M1	0		Ground CH 1
	2	AO1	0	red	Analog Output CH 1
	3	Ţ	0		Shield
	4	M0	0		Ground CH 0
	5	AO0	0	red	Analog Output CH 0
X3:	1	AO2	0	red	Analog Output CH 2
	2	M2	0		Ground CH 2
	3	Ŧ	0		Shield
	4	AO3	0	red	Analog Output CH 3
	5	M3	0		Ground CH 3
X4:	1	Ť	0		Shield
	2	Ť	0		Shield
	3	Ţ	0		Shield
	4	Ť	0		Shield
	5	Ť	0		Shield
I: Inpu	ıt   O: C	Output			

I: Input | O: Output

Input area

No byte of the input area is used by the module.

M32-1BD40 - AO 4 x 12Bit I > Parameter data

#### Output area

Addr.	Name	Byte	Function
+0	PIQ	Status of the outputs	
			■ Bit 0: Channel CH 0
			■ Bit 1: Channel CH 1
			■ Bit 2: Channel CH 2
			■ Bit 3: Channel CH 3

#### 4.4.1 Parameter data

DS - Record set for access via CPU, PROFIBUS and PROFINET

Name	Bytes	Function	Default	DS
RES0	1	reserved	00h	00h
WIBRK_EN	1	Wire-break recognition	00h	00h
CH0FN	1	Function number channel 0	31h	80h
CH1FN	1	Function number channel 1	31h	81h
CH2FN	1	Function number channel 2	31h	82h
CH3FN	1	Function number channel 3	31h	83h

# WIBRK\_EN Wire-break recognition

You also can activate the wire-break recognition for the current output range 0 ... 20mA. To ensure a safe wire-break recognition, the decimal value for the output is  $\geq$  100.

Byte	Bit 7 0
0	<ul> <li>Bit 0: Wire-break recognition channel 0 (1: on)</li> <li>Bit 1: Wire-break recognition channel 1 (1: on)</li> <li>Bit 2: Wire-break recognition channel 2 (1: on)</li> <li>Bit 3: Wire-break recognition channel 3 (1: on)</li> <li>Bit 7 4: reserved</li> </ul>

## CHxFN Function number channel x

In the following there are the measuring ranges with corresponding function number listed, which were supported by the analog module. With FFh the corresponding channel is deactivated. The formulas listed here allow you to transform an evaluated measuring value (digital value) to a value assigned to the measuring range (analog value) and vice versa.

M32-1BD40 - AO 4 x 12Bit I > Parameter data

## 0 ... 20mA

Output range	Current	Decimal	Hex	Range	Formulas
(funct. no.)	<b>(I)</b>	(D)			
0 20mA	23.52mA	32511	7EFFh	overrange	20
Siemens	20mA	27648	6C00h	nominal range	$I = D \ x \ \frac{20}{27648}$
S7 format	10mA	13824	3600h		
(31h)	0mA	0	0000h		$D = 27648 \ x \ \frac{I}{20}$
	Not possible, is lir	mited to 0mA.		underrange	20
0 20mA	25.00mA	20480	5000h	overrange	20
Siemens	20mA	16384	4000h	nominal range	$I = D x \frac{20}{16384}$
S5 format	10mA	8192	2000h		
(41h)	0mA	0	0000h		$D = 16384 \ x \ \frac{I}{20}$
	Not possible, is lir	mited to 0mA.		underrange	20

## 4 ... 20mA

Output range	Current	Decimal	Hex	Range	Formulas
(funct. no.)	<b>(I)</b>	(D)			
4 20mA	22.81mA	32511	7EFFh	overrange	$I = D \ x \ \frac{16}{27648} + 4$
Siemens	20mA	27648	6C00h	nominal range	27648
S7 format	12mA	13824	3600h		I-4
(30h)	4mA	0	0000h		$D = 27648 \ x \ \frac{I-4}{16}$
	0mA	-6912	E500h	underrange	
4 20mA	24.00mA	20480	5000h	overrange	$I = D \times \frac{16}{16384} + 4$
Siemens	20mA	16384	4000h	nominal range	$1 - D \times \frac{1}{16384} + 4$
S5 format	12mA	8192	2000h		I-4
(40h)	4mA	0	0000h		$D = 16384 \ x \ \frac{I-4}{16}$
	0mA	-4096	F000h	underrange	

M32-1BD40 - AO 4 x 12Bit I > Diagnostic data

### 4.4.2 Diagnostic data

So this module does not support interrupt functions, the diagnostics data serves information about this module. On error the corresponding channel LED of the module is activated and the error is registered in the diagnostics data.

The following errors are listed in the diagnostics data:

- Error in project engineering / parameterization
- Wire-break (if parameterized)
- External auxiliary supply missing

DS - Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

Name	Bytes	Function	Default	DS
ERR_A	1	Diagnostic	00h	01h
MODTYP	1	Module information	15h	
ERR_C	1	reserved	00h	
ERR_D	1	Diagnostic	00h	
CHTYP	1	Channel type	73h	
NUMBIT	1	Number diagnostic bits per channel	08h	
NUMCH	1	Number of channels of a module	04h	
CHERR	1	Channel error	00h	
CH0ERR	1	Channel-specific error channel 0	00h	
CH1ERR	1	Channel-specific error channel 1	00h	
CH2ERR	1	Channel-specific error channel 2	00h	
CH3ERR	1	Channel-specific error channel 3	00h	
CH4ERR CH7ERR	4	reserved	00h	
DIAG_US	4	μs ticker	00h	

#### ERR A Diagnostic

Byte	Bit 7 0
0	<ul> <li>Bit 0: set at module failure</li> <li>Bit 1: set at internal error</li> <li>Bit 2: set at external error</li> <li>Bit 3: set at channel error</li> <li>Bit 4: set at external auxiliary supply missing</li> <li>Bit 6 5: reserved</li> <li>Bit 7: set at error in parameterization</li> </ul>

M32-1BD40 - AO 4 x 12Bit I > Diagnostic data

# **MODTYP Module information**

Byte	Bit 7 0
0	■ Bit 3 0: module class
	<ul><li>– 0101b: Analog module</li><li>■ Bit 4: Channel information available</li></ul>
	■ Bit 7 5: reserved

## ERR\_D Diagnostic

Byte	Bit 7 0
0	<ul> <li>Bit 2 0: reserved</li> <li>Bit 3: set at internal diagnostics buffer overflow</li> <li>Bit 4: set at internal communication error</li> </ul>
	■ Bit 7 5: reserved

## **CHTYP Channel type**

Byte	Bit 7 0	
0	■ Bit 6 0: Channel type  - 73h: Analog output  ■ Bit 7: reserved	

## **NUMBIT Diagnostic bits**

Byte	Bit 7 0
0	Number of diagnostic bits per channel (here 08h)

## **NUMCH Channels**

Byte	Bit 7 0
0	Number of channels of the module (here 04h)

#### **CHERR Channel error**

Byte	Bit 7 0						
0	<ul> <li>Bit 0: set at error in channel group 0</li> <li>Bit 1: set at error in channel group 1</li> <li>Bit 2: set at error in channel group 2</li> <li>Bit 3: set at error in channel group 3</li> <li>Bit 7 4: reserved</li> </ul>						

## CH0ERR ... CH3ERR Channel-specific

Byte	Bit 7 0				
0	Channel-specific error channel x:				
	Bit 0: set at configuring/parameter assignment error				
	<ul><li>Bit 3 1: reserved</li><li>Bit 4: set at wire-break</li></ul>				
	■ Bit 7 5: reserved				

M32-1BD40 - AO 4 x 12Bit I > Diagnostic data

## DIAG\_US μs ticker

Byte	Bit 7 0				
03	Value of the µs ticker at the moment of the diagnostic				
	■ In the System MICRO module there is a timer (µs ticker). With PowerON the timer starts counting with 0. After 2 <sup>32</sup> -1µs the timer starts with 0 again.				

M32-1BD40 - AO 4 x 12Bit I > Technical data

## 4.4.3 Technical data

Order no.	M32-1BD40
Туре	SM M32 - Analog output
Module ID	0504 25E0
Current consumption/power loss	
Current consumption from backplane bus	70 mA
Current consumption from load voltage L+ (without load)	18 mA
Power loss	0.8 W
Technical data analog outputs	
Number of outputs	4
Cable length, shielded	200 m
Rated load voltage	DC 24 V
Reverse polarity protection of rated load voltage	✓
Current consumption from rated load voltage	-
Voltage output short-circuit protection	-
Voltage outputs	-
Min. load resistance (voltage range)	-
Max. capacitive load (current range)	-
Max. inductive load (current range)	-
Output voltage ranges	-
Operational limit of voltage ranges	-
Basic error limit voltage ranges	-
Destruction limit against external applied voltage	-
Current outputs	-
Max. in load resistance (current range)	350 Ω
Max. inductive load (current range)	10 μH
Typ. open circuit voltage current output	12 V
Output current ranges	0 mA +20 mA
	+4 mA +20 mA
Operational limit of current ranges	+/-0.4% +/-0.5%
Basic error limit current ranges	+/-0.2% +/-0.3%
Destruction limit against external applied voltage	max. 12V (30V for 1s)
Settling time for ohmic load	0.25 ms
Settling time for capacitive load	-
Settling time for inductive load	1.5 ms
Resolution in bit	12
Conversion time	2 ms all channels

VIPA System MICRO

M32-1BD40 - AO 4 x 12Bit I > Technical data

Order no.	M32-1BD40
Substitute value can be applied	no
Output data size	8 Byte
Status information, alarms, diagnostics	
Status display	yes
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	yes
Diagnostics information read-out	possible
Supply voltage display	green LED
Group error display	Bicolour green/red LED
Channel error display	red LED per channel
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Between channels and power supply	✓
Max. potential difference between circuits	-
Max. potential difference between inputs (Ucm)	-
Max. potential difference between Mana and Mintern (Uiso)	DC 75 V/ AC 50 V
Max. potential difference between inputs and Mana (Ucm)	-
Max. potential difference between inputs and Mintern (Uiso)	-
Max. potential difference between Mintern and outputs	-
Insulation tested with	DC 500 V
Datasizes	
Input bytes	0
Output bytes	8
Parameter bytes	10
Diagnostic bytes	20
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	26 mm x 88 mm x 71 mm
Net weight	94 g

M32-1BD40 - AO 4 x 12Bit I > Technical data

Order no.	M32-1BD40
Weight including accessories	94 g
Gross weight	107 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	in preparation
KC certification	in preparation

M32-1BD70 - AO 4 x 12Bit U

#### 4.5 M32-1BD70 - AO 4 x 12Bit U

#### **Properties**

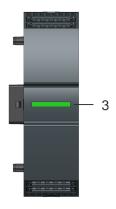
The Analog module has 4 outputs with parameterizable functions. The channels of the module are electrically isolated from the backplane bus. In addition, the channels are isolated to the DC 24V power supply by means of DC/DC converter.

- 4 analog outputs
- Suited for sensors with ±10V, 0 ... 10V
- Diagnostics function
- 12bit resolution

#### **Structure**



- 1 X2: Terminal (DC 24V)
- 2 X1: Terminal (AO 0, AO 1)
- 3 Status bar periphery module 4 X3: Terminal (AO 2, AO 3)
- 5 X4: Terminal (Shield)
- 6 X2 1L+: LED DC 24V electronic section supply
- 7 X1 AO 0, AO 1: LED channel error
- 8 X3 AO 2, AO 3: LED channel error





## Status bar

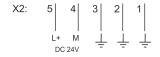
LED	Description
	LEDs green on: Backplane bus communication and module status are OK
	LED red on: Module reports an error
	LED red blinks with 1Hz: Error in configuration
	LEDs green are blinking with 1Hz: Error backplane bus communication

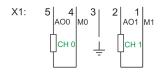
M32-1BD70 - AO 4 x 12Bit U

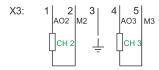
#### **LEDs** connectors

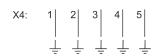
Pin	Function	LED	Description
X2:5	L+	green	DC 24V electronic section supply OK
X1:5	AO 0	red	Error channel x
X1:2	AO 1	red	Error in parameterization
X3:1	AO 2	red	Wire break (if parameterized)
X3:4	AO 3	red	

## Pin assignment









	Pin	Function	Type	LED	Description
X2:	1	<u>‡</u>	0		Shield
	2	Ť	0		Shield
	3	Ť	I		Shield
	4	M	I		Ground power supply (M)
	5	L+	I	green	Power supply DC 24V (L+)
X1:	1	M1	0		Ground CH 1
	2	AO1	0	red	Analog Output CH 1
	3	Ť	0		Shield
	4	M0	0		Ground CH 0
	5	AO0	0	red	Analog Output CH 0
X3:	1	AO2	0	red	Analog Output CH 2
	2	M2	0		Ground CH 2
	3	Ţ	0		Shield
	4	AO3	0	red	Analog Output CH 3
	5	M3	0		Ground CH 3
X4:	1	Ţ	0		Shield
	2	Ţ	0		Shield
	3	Ţ	0		Shield
	4	<u> </u>	0		Shield
	5	Ţ	0		Shield
I: Input I O: Output					

I: Input | O: Output

Input area

No byte of the input area is used by the module.

M32-1BD70 - AO 4 x 12Bit U > Parameter data

#### **Output area**

Addr.	Name	Byte	Function
+0	PIQ	0	Status of the outputs
			■ Bit 0: Channel CH 0
			■ Bit 1: Channel CH 1
			■ Bit 2: Channel CH 2
			■ Bit 3: Channel CH 3

#### 4.5.1 Parameter data

DS - Record set for access via CPU, PROFIBUS and PROFINET

Name	Bytes	Function	Default	DS
RES0	1	reserved	00h	00h
SHORT_EN	1	Short-circuit recognition	00h	00h
CH0FN	1	Function number channel 0	12h	80h
CH1FN	1	Function number channel 1	12h	81h
CH2FN	1	Function number channel 2	12h	82h
CH3FN	1	Function number channel 3	12h	83h

# SHORT\_EN Short-circuit recognition

Byte	Bit 7 0
0	<ul> <li>Bit 0: Short-circuit recognition channel 0 (1: on)</li> <li>Bit 1: Short-circuit recognition channel 1 (1: on)</li> <li>Bit 2: Short-circuit recognition channel 2 (1: on)</li> <li>Bit 3: Short-circuit recognition channel 3 (1: on)</li> <li>Bit 7 4: reserved</li> </ul>

# **CHxFN Function number** channel x

In the following there are the measuring ranges with corresponding function number listed, which were supported by the analog module. With FFh the corresponding channel is deactivated. The formulas listed here allow you to transform an evaluated measuring value (digital value) to a value assigned to the measuring range (analog value) and vice versa.

M32-1BD70 - AO 4 x 12Bit U > Parameter data

## ±10V

Output range (funct. no.)	Voltage (U)	Decimal (D)	Hex	Range	Formulas
±10V	11.76V	32511	7EFFh	overrange	10
Siemens S format	10V	27648	6C00h	nominal range	$U = D x \frac{10}{27648}$
(12h)	5V	13824	3600h		17
	0V	0	0000h		$D = 27648 \ x \ \frac{U}{10}$
	-5V	-13824	CA00h		
	-10V	-27648	9400h		
	-11.76V	-32512	8100h	underrange	
±10V	12.5V	20480	5000h	overrange	U = D × 10
Siemens S5 format (22h)	10V	16384	4000h	nominal range	$U = D \ x \ \frac{10}{16384}$
	5V	8192	2000h		II.
	0V	0	0000h		$D = 16384 \ x \ \frac{U}{10}$
	-5V	-8192	E000h		
	-10V	-16384	C000h		
	-12.5V	-20480	B000h	underrange	

## 0 ... 10V

Output range	Voltage	Decimal	Hex	Range	Formulas
(funct. no.)	(U)	(D)			
0 10V	11,76V	32511	7EFFh	overrange	U = D × 10
Siemens	10V	27648	6C00h	nominal range	$U = D x \frac{10}{27648}$
S7 format	5V	13824	3600h		11
(10h)	0V	0	0000h		$D = 27648 \ x \ \frac{U}{10}$
	Not possible, is lir	mited to 0V.		underrange	
0 10V	12,5V	20480	5000h	overrange	U - D x
Siemens	10V	16384	4000h	nominal range	$U = D x \frac{10}{16384}$
S5 format	5V	8192	2000h		11
(20h)	0V	0	0000h		$D = 16384 \ x \ \frac{U}{10}$
	Not possible, is lir	nited to 0V.		underrange	

M32-1BD70 - AO 4 x 12Bit U > Diagnostic data

### 4.5.2 Diagnostic data

So this module does not support interrupt functions, the diagnostics data serves information about this module. On error the corresponding channel LED of the module is activated and the error is registered in the diagnostics data.

The following errors are listed in the diagnostics data:

- Error in project engineering / parameterization
- Short-circuit/overload (if parameterized)
- DS Record set for access via CPU, PROFIBUS and PROFINET. The access happens by DS 01h. Additionally the first 4 bytes may be accessed by DS 00h.

Name	Bytes	Function	Default	DS
ERR_A	1	Diagnostic	00h	01h
MODTYP	1	Module information	15h	
ERR_C	1	reserved	00h	
ERR_D	1	Diagnostic	00h	
CHTYP	1	Channel type	73h	
NUMBIT	1	Number diagnostic bits per channel	08h	
NUMCH	1	Number of channels of a module	04h	
CHERR	1	Channel error	00h	
CH0ERR	1	Channel-specific error channel 0	00h	
CH1ERR	1	Channel-specific error channel 1	00h	
CH2ERR	1	Channel-specific error channel 2	00h	
CH3ERR	1	Channel-specific error channel 3	00h	
CH4ERR CH7ERR	4	reserved	00h	
DIAG_US	4	μs ticker	00h	

#### ERR\_A Diagnostic

Byte	Bit 7 0
0	<ul> <li>Bit 0: set at module failure</li> <li>Bit 1: set at internal error</li> <li>Bit 2: set at external error</li> <li>Bit 3: set at channel error</li> <li>Bit 4: set at external auxiliary supply missing</li> <li>Bit 6 5: reserved</li> <li>Bit 7: set at error in parameterization</li> </ul>

M32-1BD70 - AO 4 x 12Bit U > Diagnostic data

# **MODTYP Module information**

Byte	Bit 7 0
0	■ Bit 3 0: module class
	<ul><li>– 0101b: Analog module</li><li>■ Bit 4: Channel information available</li></ul>
	■ Bit 7 5: reserved

## ERR\_D Diagnostic

Byte	Bit 7 0
0	<ul> <li>Bit 2 0: reserved</li> <li>Bit 3: set at internal diagnostics buffer overflow</li> <li>Bit 4: set at internal communication error</li> </ul>
	■ Bit 7 5: reserved

## **CHTYP Channel type**

Byte	Bit 7 0
0	<ul> <li>Bit 6 0: Channel type</li> <li>73h: Analog output</li> <li>Bit 7: reserved</li> </ul>

## **NUMBIT Diagnostic bits**

Byte	Bit 7 0
0	Number of diagnostic bits per channel (here 08h)

## **NUMCH Channels**

Byte	Bit 7 0
0	Number of channels of the module (here 04h)

#### **CHERR Channel error**

Byte	Bit 7 0
0	<ul> <li>Bit 0: set at error in channel group 0</li> <li>Bit 1: set at error in channel group 1</li> <li>Bit 2: set at error in channel group 2</li> <li>Bit 3: set at error in channel group 3</li> <li>Bit 7 4: reserved</li> </ul>

## CH0ERR ... CH3ERR Channel-specific

Byte	Bit 7 0
0	Channel-specific error channel x:
	■ Bit 0: set at configuring/parameter assignment error
	■ Bit 2 1: reserved
	■ Bit 3: set at short-circuit to ground
	■ Bit 7 4: reserved

M32-1BD70 - AO 4 x 12Bit U > Diagnostic data

## DIAG\_US μs ticker

Byte	Bit 7 0	
03	Value of the µs ticker at the moment of the diagnostic	
	■ In the System MICRO module there is a timer (μs ticker). With PowerON the timer starts counting with 0. After 2 <sup>32</sup> -1μs the timer starts with 0 again.	

M32-1BD70 - AO 4 x 12Bit U > Technical data

## 4.5.3 Technical data

Order no.	M32-1BD70
Туре	SM M32 - Analog output
Module ID	050A 25E0
Current consumption/power loss	
Current consumption from backplane bus	60 mA
Current consumption from load voltage L+ (without load)	25 mA
Power loss	0.9 W
Technical data analog outputs	
Number of outputs	4
Cable length, shielded	200 mm
Rated load voltage	DC 24 V
Reverse polarity protection of rated load voltage	✓
Current consumption from rated load voltage	-
Voltage output short-circuit protection	✓
Voltage outputs	✓
Min. load resistance (voltage range)	5 kΩ
Max. capacitive load (current range)	1 μF
Max. inductive load (current range)	10 mA
Output voltage ranges	-10 V +10 V
	0 V +10 V
Operational limit of voltage ranges	+/-0.3%
Basic error limit voltage ranges	+/-0.2%
Destruction limit against external applied voltage	max. 24V
Current outputs	-
Max. in load resistance (current range)	-
Max. inductive load (current range)	-
Typ. open circuit voltage current output	-
Output current ranges	-
Operational limit of current ranges	-
Basic error limit current ranges	-
Destruction limit against external applied voltage	-
Settling time for ohmic load	2 ms
Settling time for capacitive load	4 ms
Settling time for inductive load	-
Resolution in bit	12
Conversion time	2 ms all channels

VIPA System MICRO

M32-1BD70 - AO 4 x 12Bit U > Technical data

Order no.	M32-1BD70
Substitute value can be applied	no
Output data size	8 Byte
Status information, alarms, diagnostics	
Status display	yes
Interrupts	no
Process alarm	no
Diagnostic interrupt	no
Diagnostic functions	yes
Diagnostics information read-out	possible
Supply voltage display	green LED
Group error display	Bicolour green/red LED
Channel error display	red LED per channel
Isolation	
Between channels	-
Between channels of groups to	-
Between channels and backplane bus	✓
Between channels and power supply	✓
Max. potential difference between circuits	-
Max. potential difference between inputs (Ucm)	-
Max. potential difference between Mana and Mintern (Uiso)	DC 75 V/ AC 50 V
Max. potential difference between inputs and Mana (Ucm)	-
Max. potential difference between inputs and Mintern (Uiso)	-
Max. potential difference between Mintern and outputs	-
Insulation tested with	DC 500 V
Datasizes	
Input bytes	0
Output bytes	8
Parameter bytes	10
Diagnostic bytes	20
Housing	
Material	PPE / PPE GF10
Mounting	Profile rail 35 mm
Mechanical data	
Dimensions (WxHxD)	26 mm x 88 mm x 71 mm
Net weight	94 g

M32-1BD70 - AO 4 x 12Bit U > Technical data

Order no.	M32-1BD70
Weight including accessories	94 g
Gross weight	107 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL certification	in preparation
KC certification	in preparation